
Computational complexity of solution concepts

UNIVERSITÀ DELLA CALABRIA



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Part I: P vs NP

One Basic Question...

- The lost letter...
 - Year: 1956
 - To: John von Neumann
- ...and one question

$P=NP?$



Kurt Gödel (1906-1978)

Millennium Prize Problems

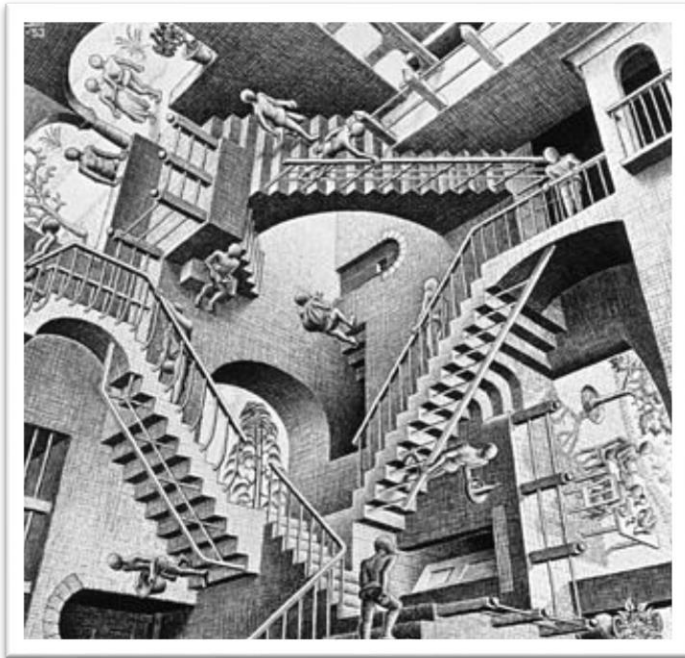
- Seven problems

- ❑ **P versus NP**
- ❑ Poincaré conjecture
- ❑ Hodge conjecture
- ❑ Riemann hypothesis
- ❑ Yang–Mills existence and mass gap
- ❑ Navier–Stokes existence and smoothness
- ❑ Birch and Swinnerton-Dyer conjecture

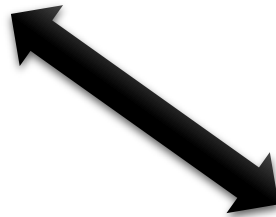
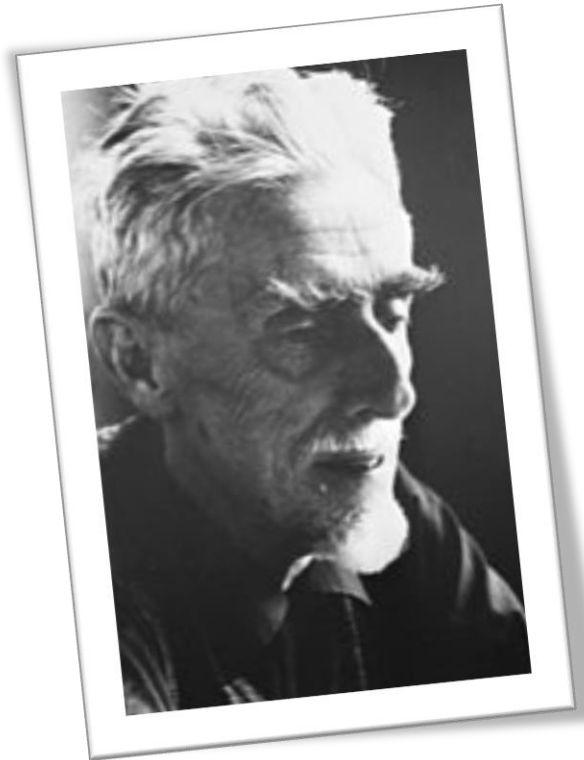


CLAY
MATHEMATICS
INSTITUTE

About Clay



M. C. ESCHER
RELATIVITY, 1953



CLAY
MATHEMATICS
INSTITUTE

About the Problems

- One problem has been solved in 2006
 - Poincaré conjecture



- ▶ He did not want the prize...
- ▶ ...and the Fields Medal



GRIGORY PERELMAN

Problems

- Look for a document



INPUT



OUTPUT

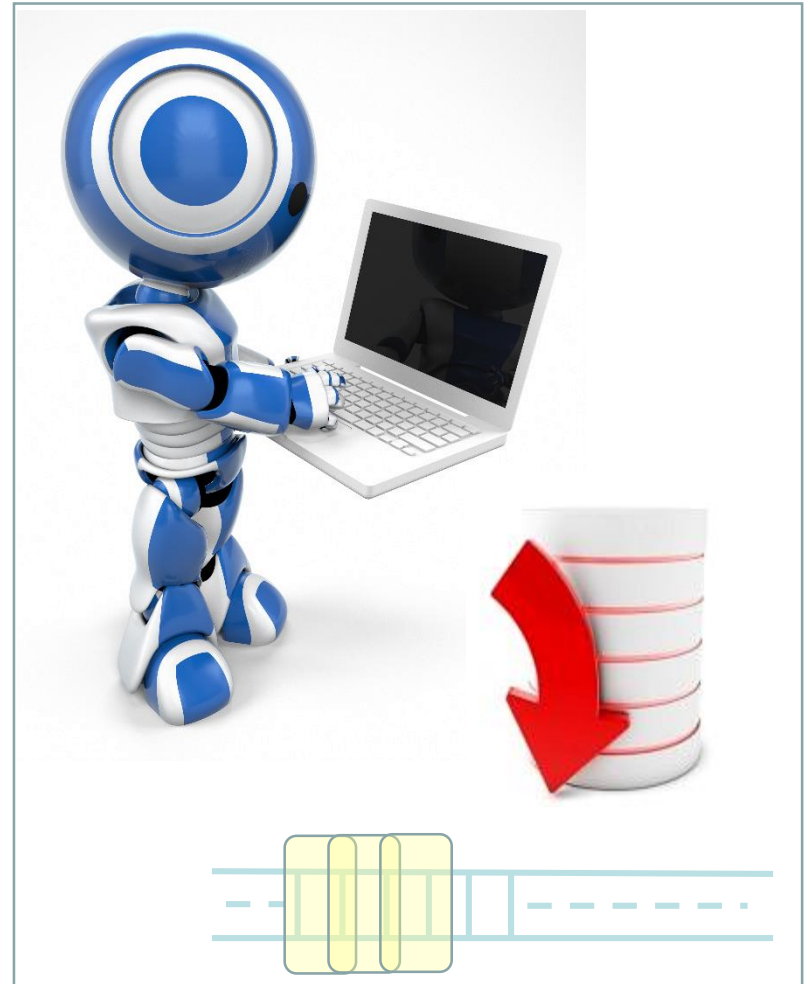


Algorithms

- Look for a document



INPUT

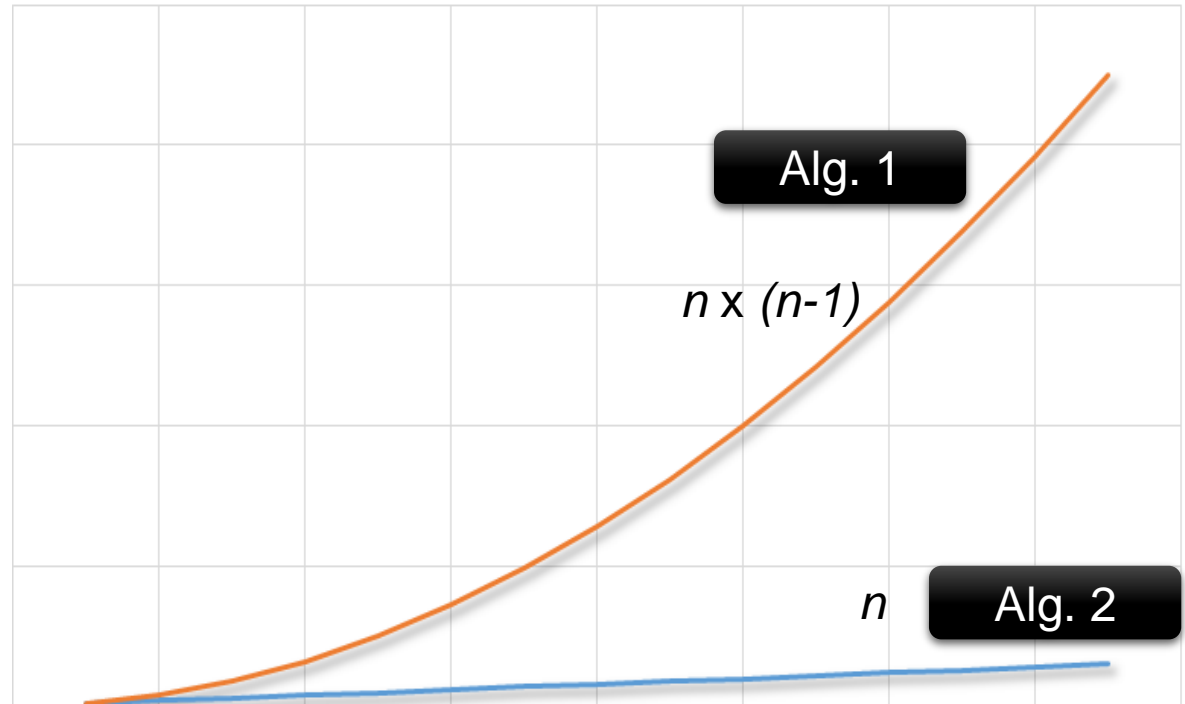


OUTPUT



Comparison

- Algorithm 1
 - «quadratic»
- Algorithm 2
 - «linear»



The problem is in **P** (Polynomial)

Look at the Pictures



Look at the Pictures



Golden Ratio

Golden Ratio

$$\frac{L}{R} = \frac{R+L}{L}$$

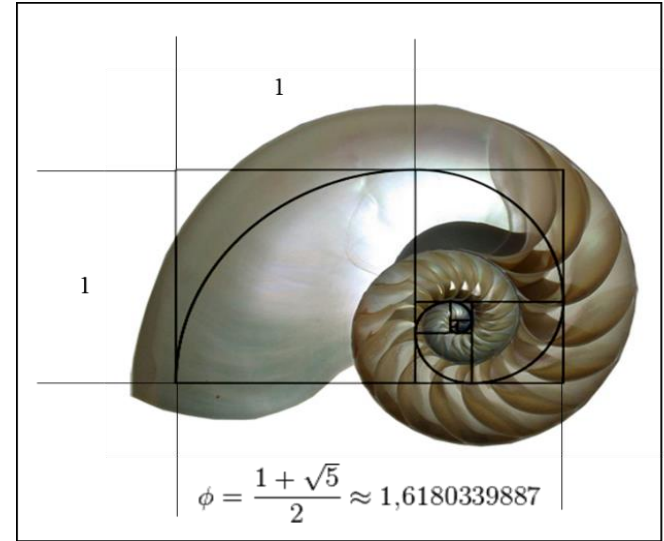


R=1

$$L = \frac{1+L}{L}$$



$$L^2 - L - 1 = 0$$



Golden Ratio

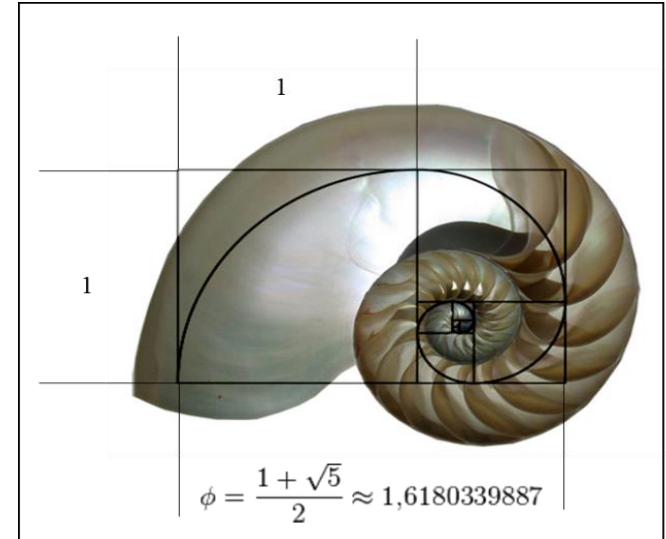
$$\frac{L}{R} = \frac{R+L}{L}$$



$$L = \frac{1+L}{L}$$



$$L^2 - L - 1 = 0$$



- Does there exist a solution?
- More generally, take L_1, L_2, \dots, L_n and answer questions such as:
 - Is there some value for L_1 such that for all values for $L_2 \dots$

Golden Ratio

- Provably **EXP**ponential
- Every algorithm takes 10^n operations in the worst case

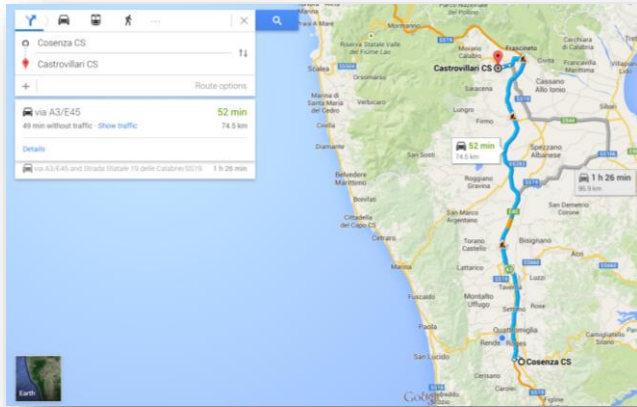
- Does there exist a solution?
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Orders of Magnitude

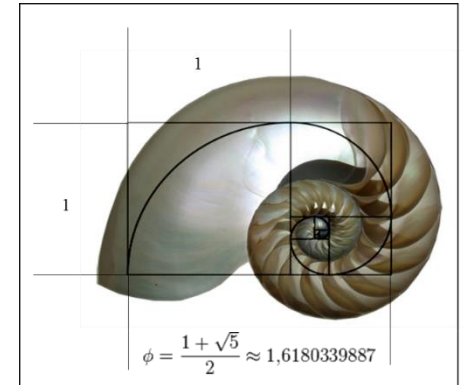
- 10^4 : There are 20,000–40,000 distinct Chinese characters
- 10^5 : 67,000 words in James Joyce's Ulysses
- 10^6 : As of August 31, 2015, Wikipedia contains approximately 4956000 articles in the English language
- 10^9 : Approximate population of India in 2011
- 10^{14} : Cells in the human body
- 10^{21} : Estimated number of observable stars
- 10^{80} : Atoms in the Universe



Classes of Problems



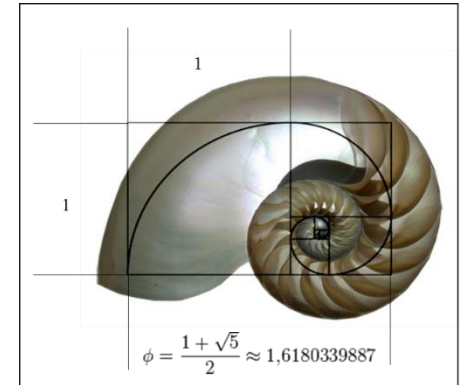
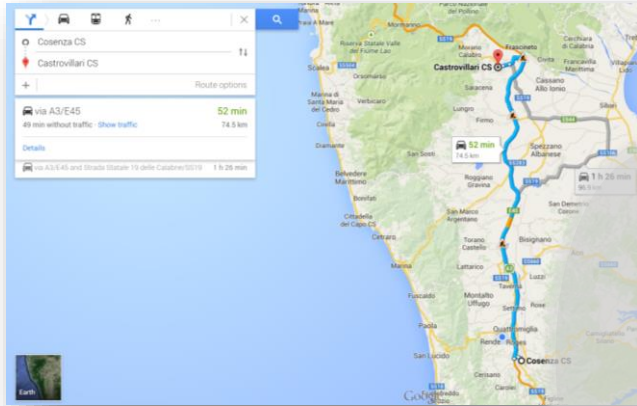
P



EXP



Classes of Problems



P

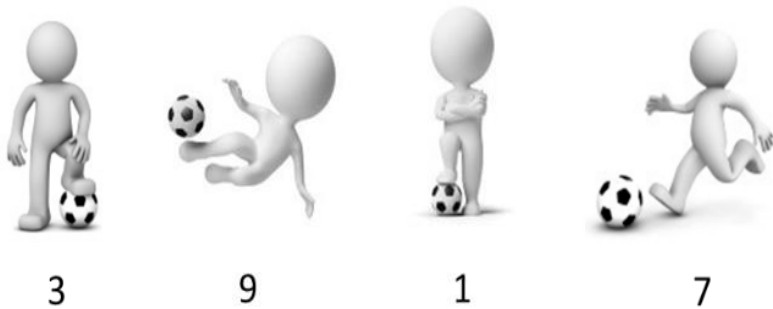
EXP

NP



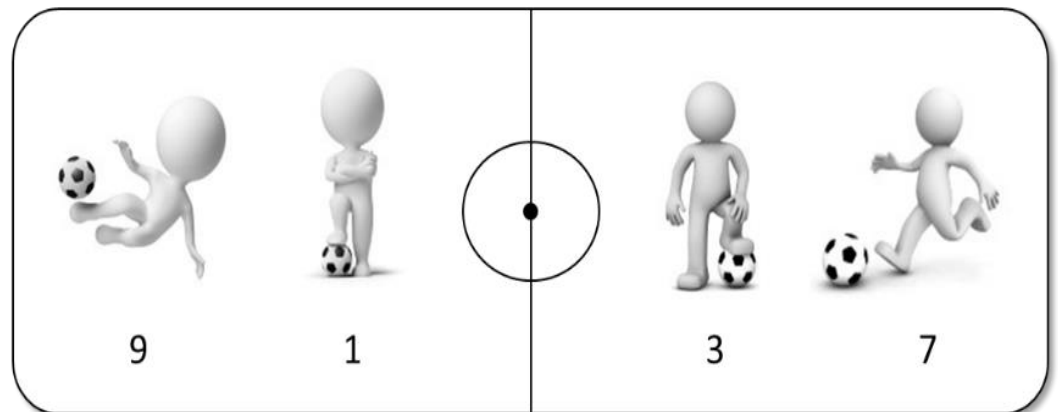
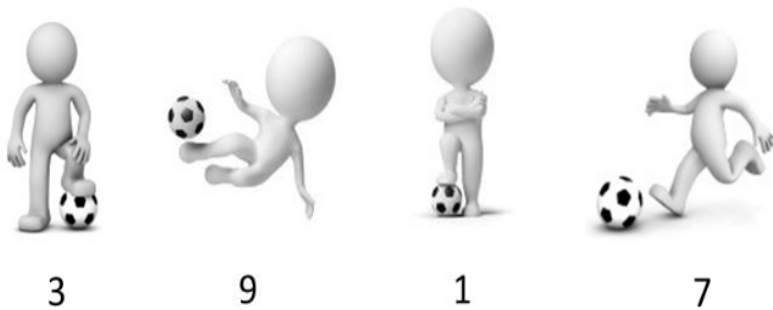
A Simple Problem for NP

- We would like to set up two teams
- Goal
 - The teams should be «balanced»



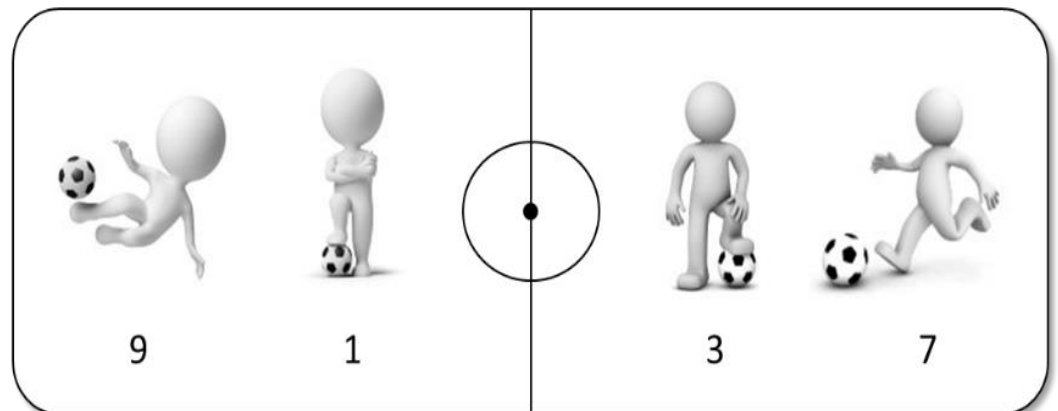
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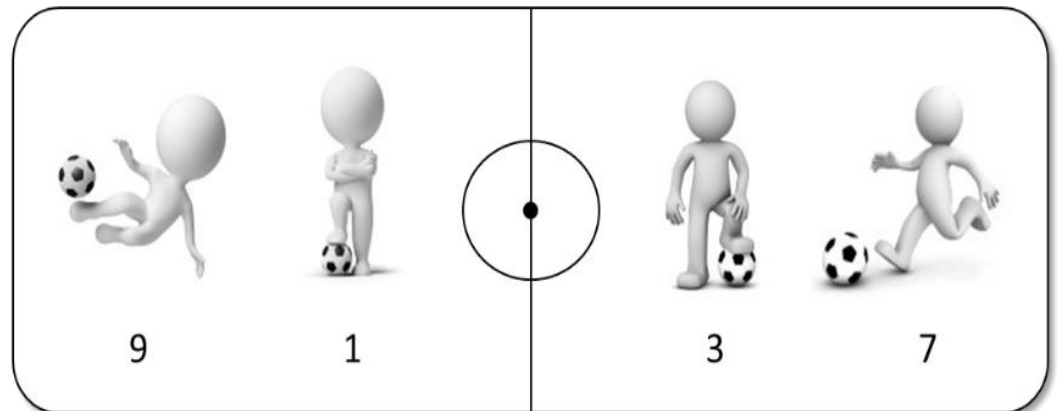
A Simple Problem for NP

- We would like to set up two teams
- Goal
 - The teams should be «balanced»
- Algorithm
 - Consider all possible teams



A Simple Problem for NP

- We would like to set up two teams
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- Algorithm
 - Consider all possible teams



Further Examples

- Scheduling
- Planning
- Logistics
- Crypto

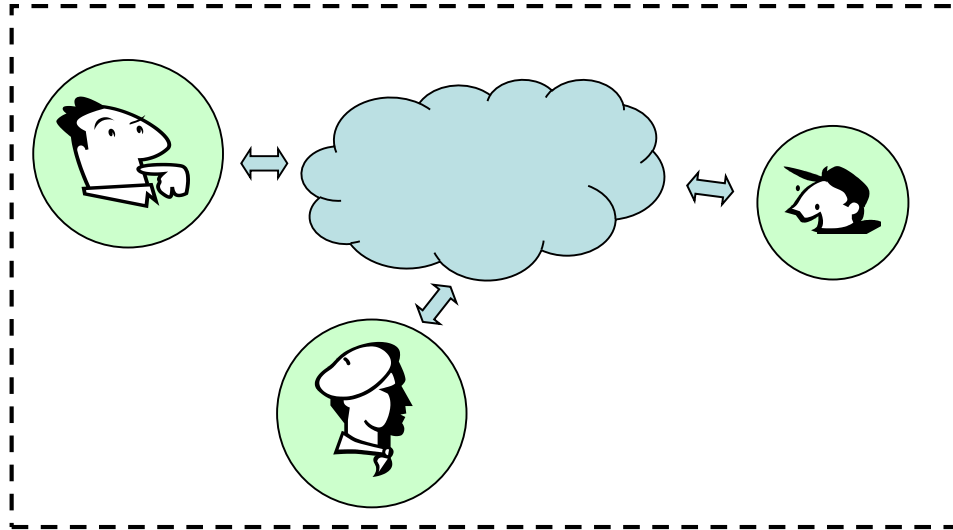


- ...Game Theory



Part II: Nash Equilibria

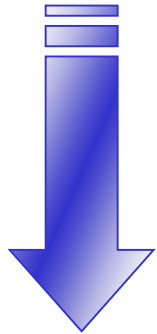
Game Theory (in a Nutshell)



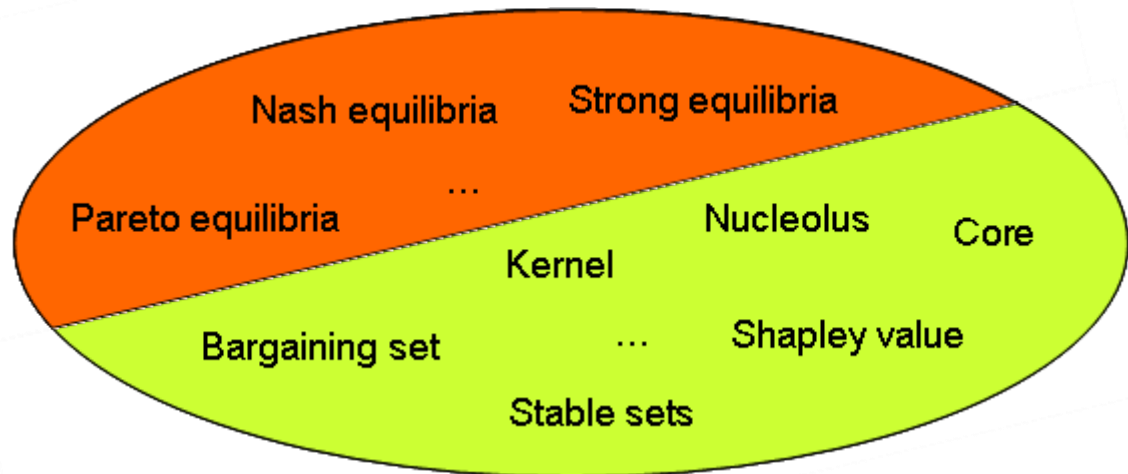
Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- Is **rational**

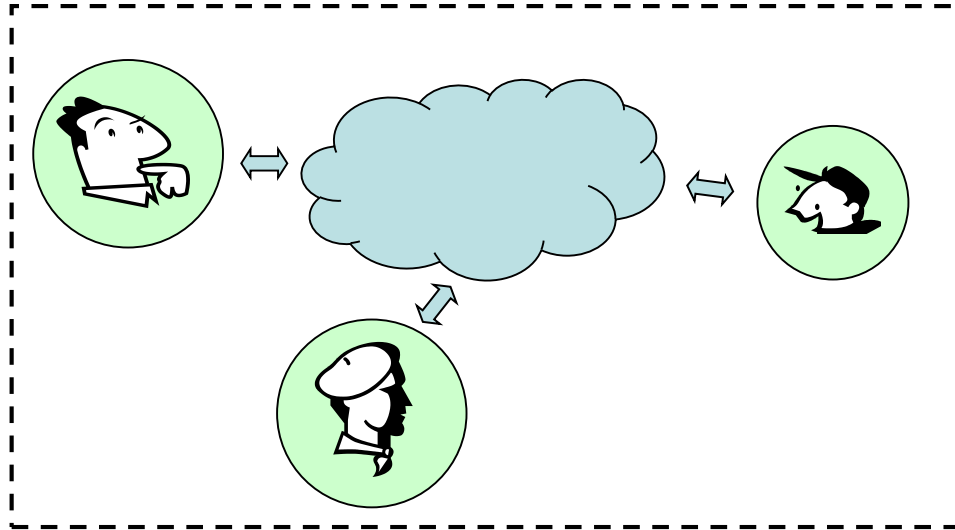
Which actions have to be performed?



Solution Concepts



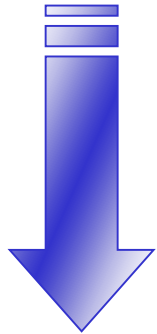
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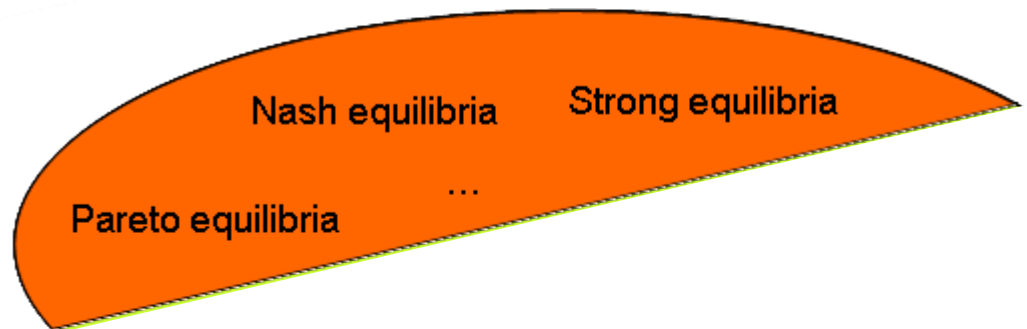
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Which actions have to be performed?



Solution Concepts



Non-Cooperative Games_(1/3)

Payoff maximization problem

Each player:

- Has a **goal** to be achieved
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Bob	John goes <i>out</i>	John stays at <i>home</i>
<i>out</i>	2	0
<i>home</i>	0	1

John	Bob goes <i>out</i>	Bob stays at <i>home</i>
<i>out</i>	1	1
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Non-Cooperative Games_(2/3)

Payoff maximization problem

Nash equilibria

Each player:

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Non-Cooperative Games_(3/3)

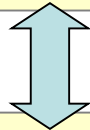
Payoff maximization problem

Nash equilibria

Each player:

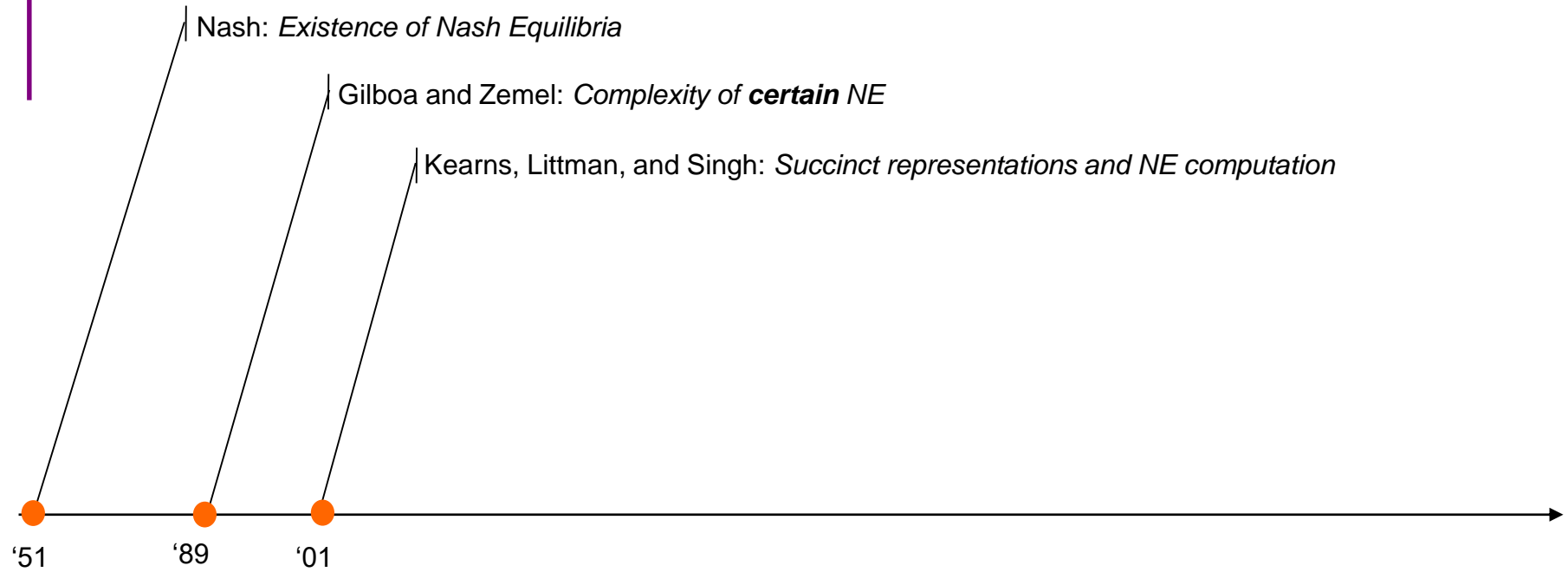
- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- Is **rational**

pure Nash equilibria



Every game admits a *mixed Nash equilibrium*,

- where players chose their strategies according to probability distributions



Succinct Game Representations

- Players:
 - Maria, Francesco
- Choices:
 - movie, opera

If 2 players, then size = 2^2

Maria	Francesco, <i>movie</i>	Francesco, <i>opera</i>
<i>movie</i>	2	0
<i>opera</i>	0	1

Succint Game Representations

- **Players:**
 - Maria, Francesco, Paola
- **Choices:**
 - movie, opera

If 2 players, then size = 2^2

If 3 players, then size = 2^3

Maria	$F_{\text{movie}} \text{ and } P_{\text{movie}}$	$F_{\text{movie}} \text{ and } P_{\text{opera}}$	$F_{\text{opera}} \text{ and } P_{\text{movie}}$	$F_{\text{opera}} \text{ and } P_{\text{opera}}$
<i>movie</i>	2	0	2	1
<i>opera</i>	0	1	2	2

Succint Game Representations

- **Players:**
 - Maria, Francesco, Paola, Roberto, and Giorgio
- **Choices:**
 - movie, opera

If 2 players, then size = 2^2

If 3 players, then size = 2^3

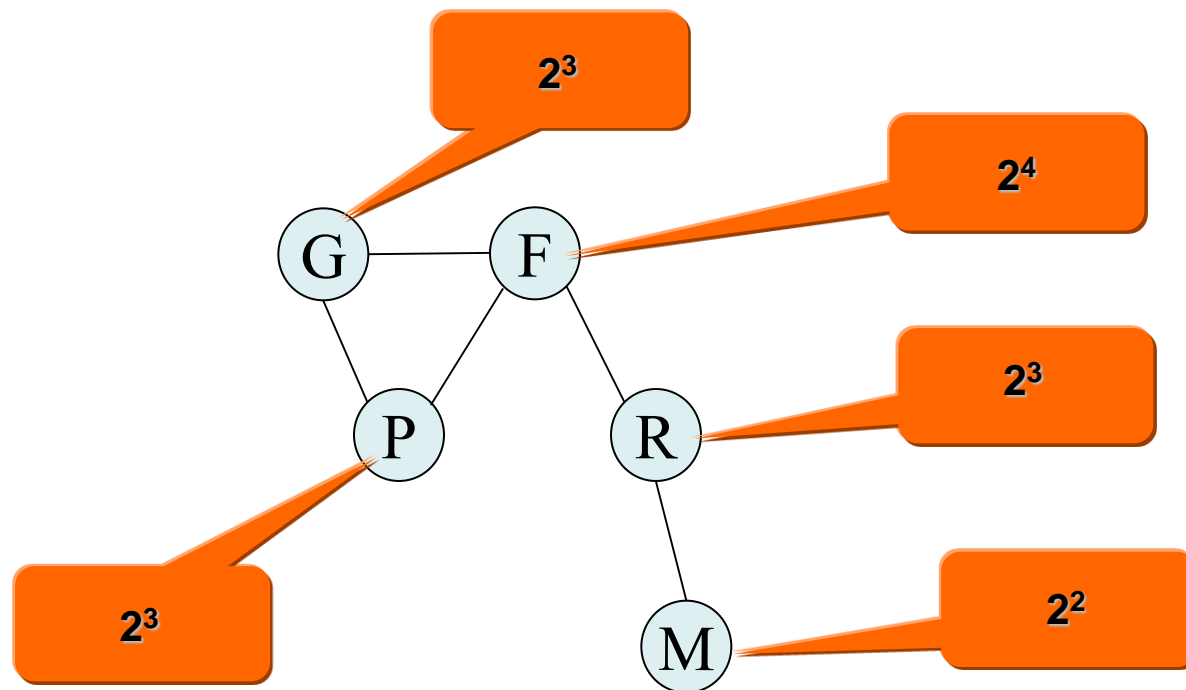
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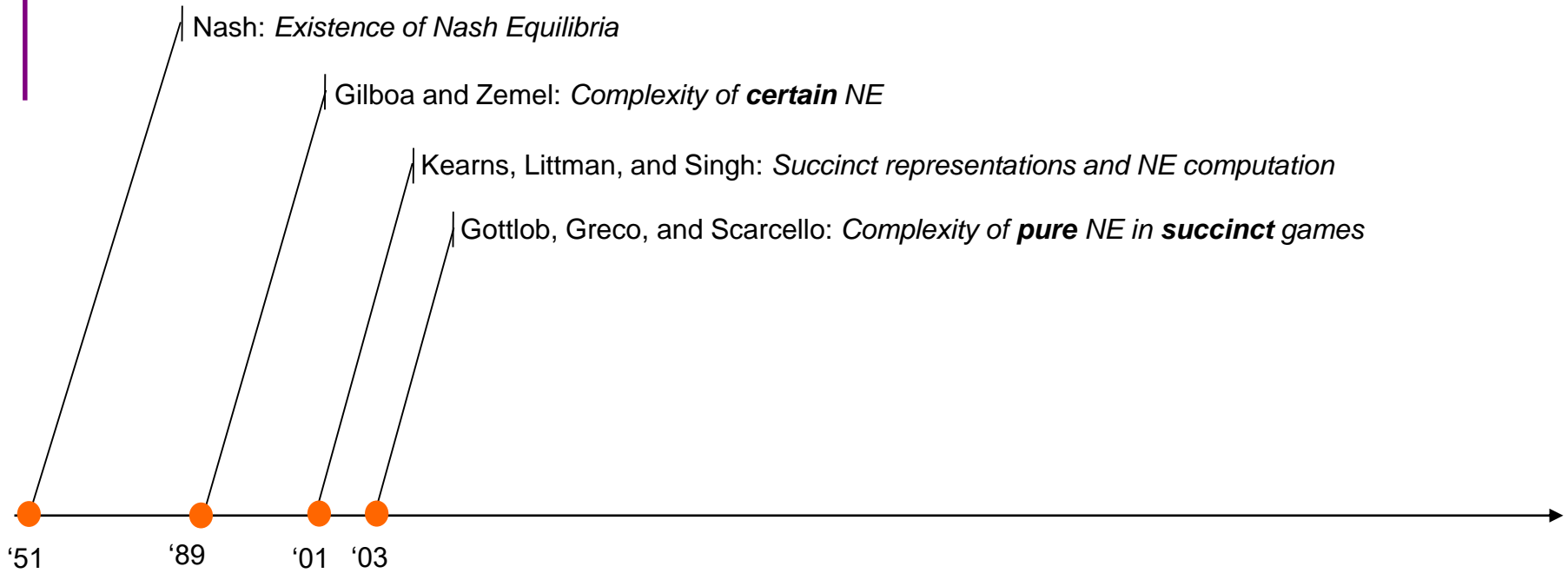
If N players, then size = 2^N

Maria	F_{movie} and P_{movie} and R_{movie} and G_{movie}
<i>movie</i>	2
<i>opera</i>	0

Succinct Game Representations

- **Players:**
 - Francesco, Paola, Roberto, Giorgio, and Maria
- **Choices:**
 - movie, opera





Complexity of Pure Nash Equilibria_(1/3)

■ Game Representation

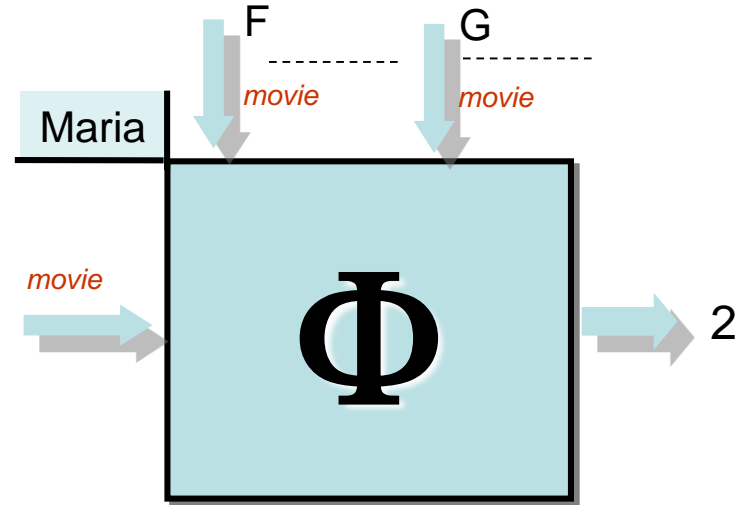
- Tables
- Arbitrary Functions

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Complexity of Pure Nash Equilibria_(1/3)

■ Game Representation

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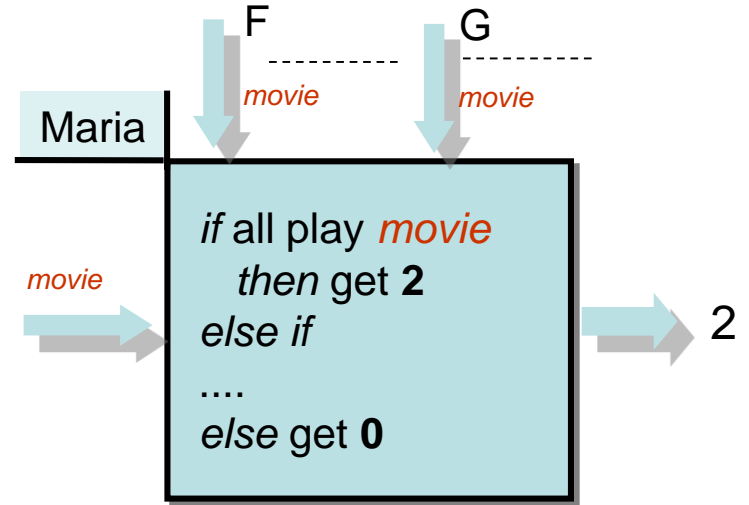


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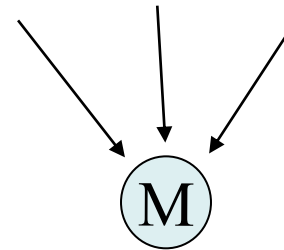
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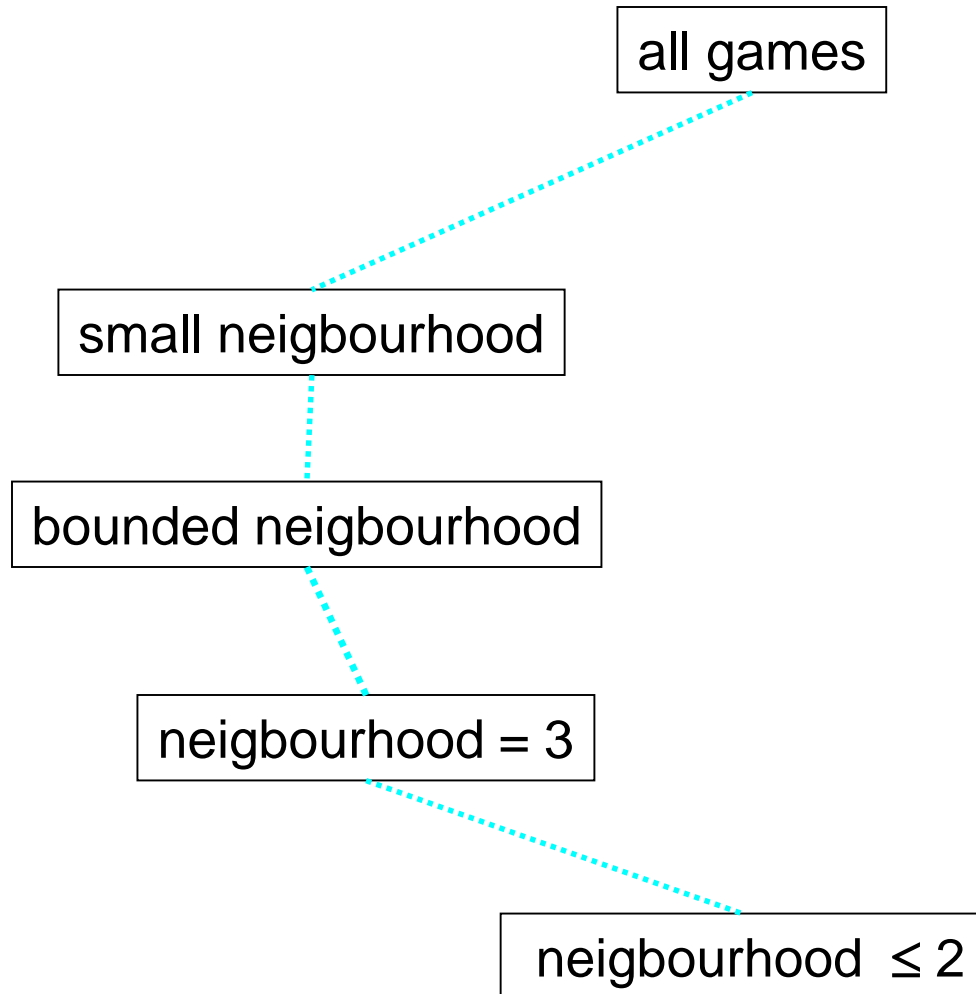
- Tables
- Arbitrary Functions

■ Neighborhood

- Arbitrary
- Small (i.e., log)
- Bounded (i.e., constant)



Complexity of Pure Nash Equilibria_(3/3)



Complexity of Pure Nash Equilibria_(3/3)

THE BAD NEWS:

NP-c all games

NP-c small neighbourhood

NP-c bounded neighbourhood

NP-c neighbourhood = 3

polynomial

neighbourhood ≤ 2

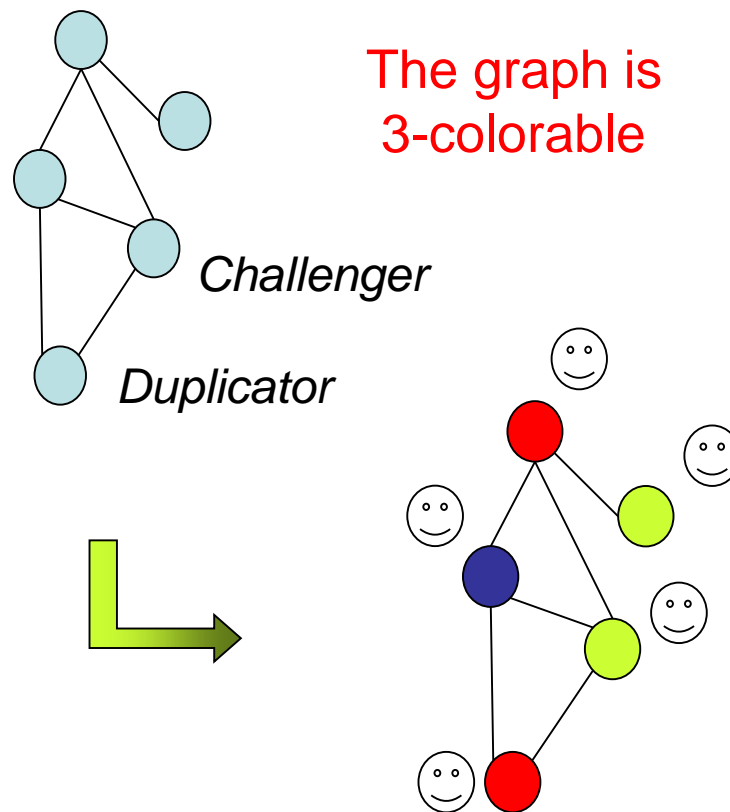
```
graph TD; A["NP-c all games"] -.-> B["NP-c small neighbourhood"]; B -.-> C["NP-c bounded neighbourhood"]; C -.-> D["NP-c neighbourhood = 3"]; D -.-> E["polynomial neighbourhood ≤ 2"];
```

Hard Games: NP-hardness

Theorem Deciding whether a game has pure Nash equilibrium is NP-complete. Hardness holds even if the game is in GNF, and if it has 3-bounded neighborhood.

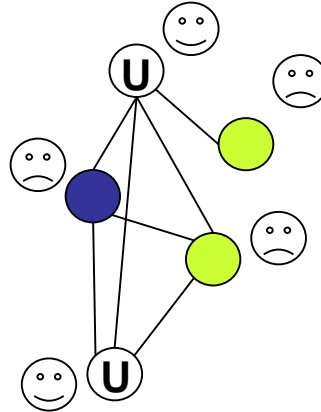
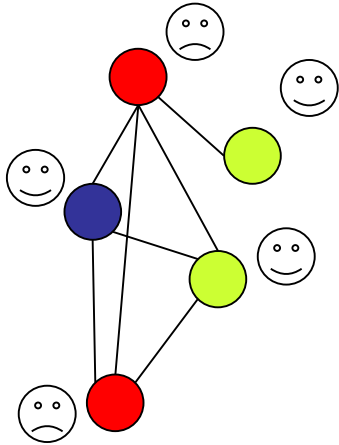
Reduction from 3-colorability

- **Players:** Nodes
- **Actions:** Colors + $\{U, V\}$
- **Utility Functions:** the players have an incentive to play a color different from the ones played by the neighbors
- **Challenger** and **Duplicator** are distinguished (connected) players such that:
 - C wants to play an action different from D ;
 - D want to play either a color different from C , or the same action in $\{U, V\}$.



Hard Games: NP-hardness

The graph is **not** 3-colorable:

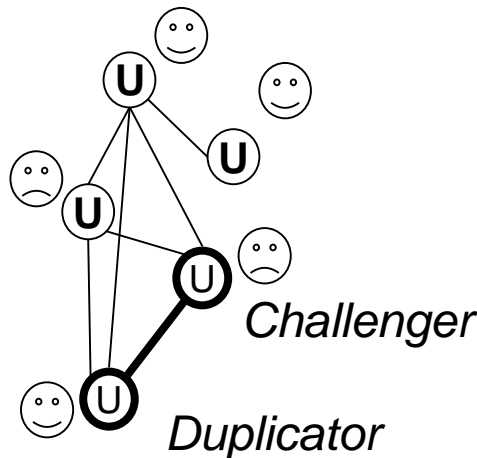
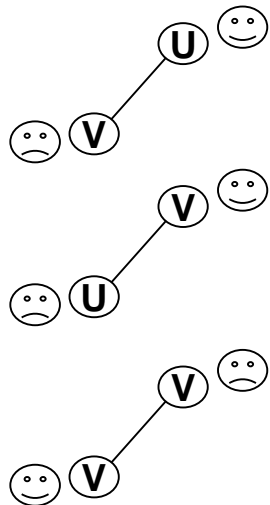


□ Adjacent players playing the same color have an incentive to play U.

□ The neighbors of players playing U have an incentive to play U, in their turn.

□ Challenger want to plays an action different of Duplicator.

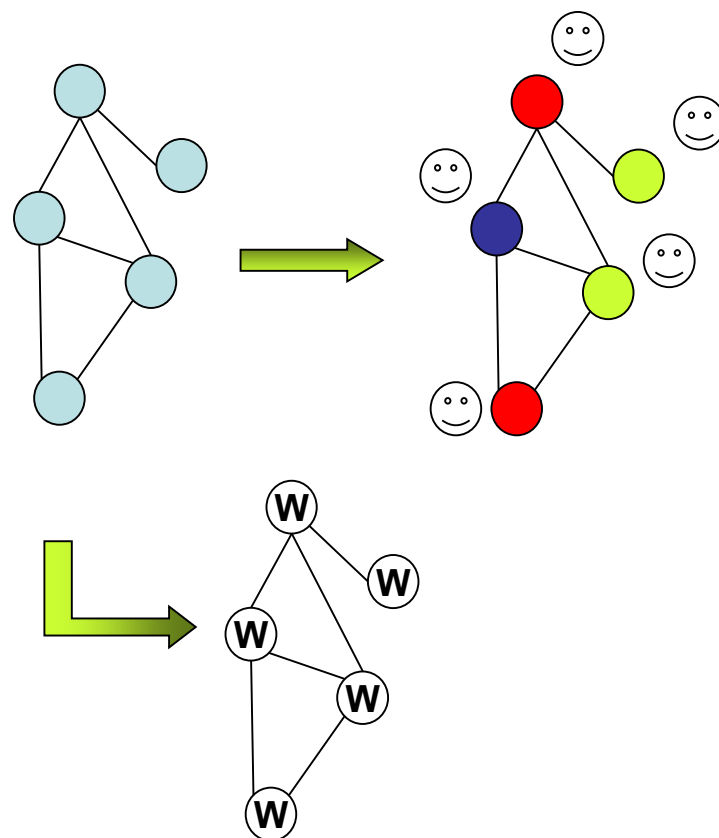
□ No Nash equilibria exist.

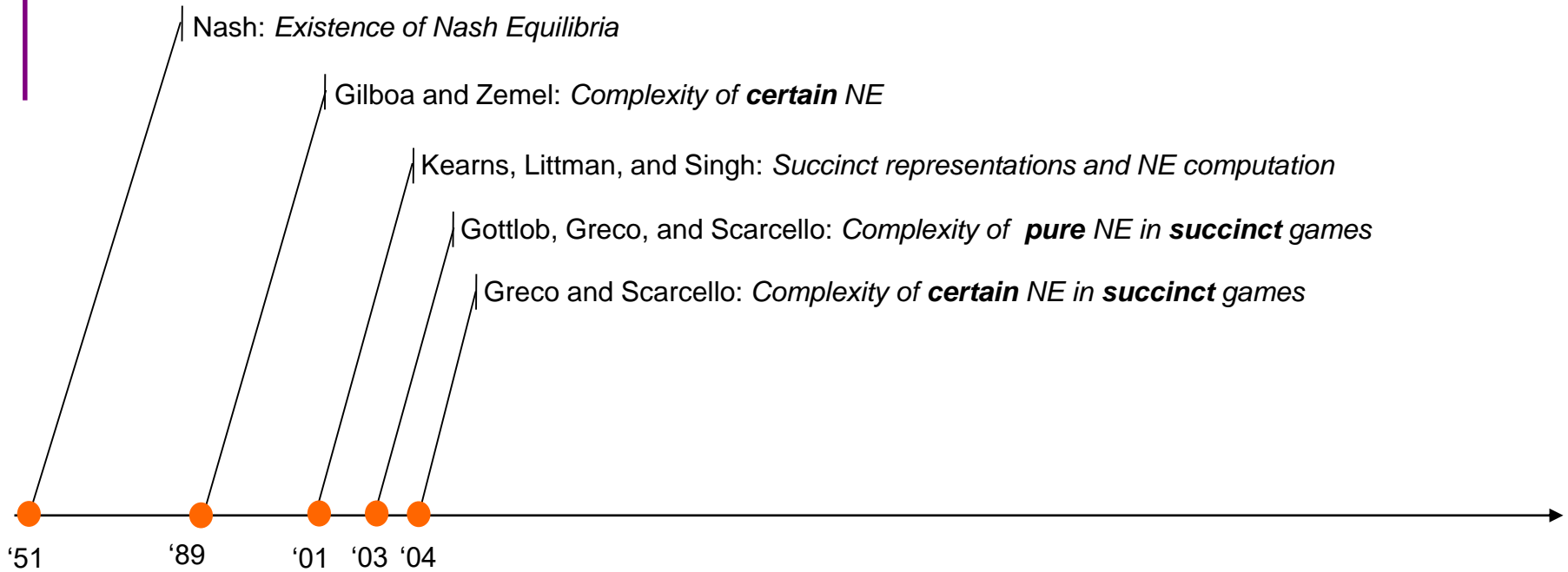


Hard Games: coNP-hardness

Theorem Deciding whether a global strategy \mathbf{x} is a Pareto (Strong) Nash equilibrium is coNP-complete. Hardness holds even if \mathbf{x} is a Nash equilibrium, the game is in GNF, and if it has 3-bounded neighborhood.

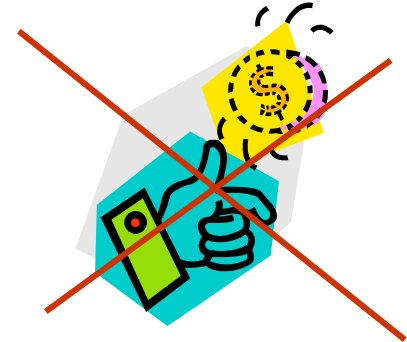
- **Reduction from 3-non-colorability**
- **The same construction as above except:**
 - Each player may play also W, and has an incentive in such choice if all her neighbors play W, too.
- **There is always a Nash equilibrium where all players play W**
 - Utility functions are such that it this equilibrium is not preferred to the equilibrium (if any) corresponding to a 3-coloring.
 - This equilibrium is Pareto iff the graph is not 3-colorable.





Constrained Nash Equilibria_(1/3)

Bob	John goes <i>out</i>	John stays at <i>home</i>
<i>out</i>	1	0
<i>home</i>	0	1

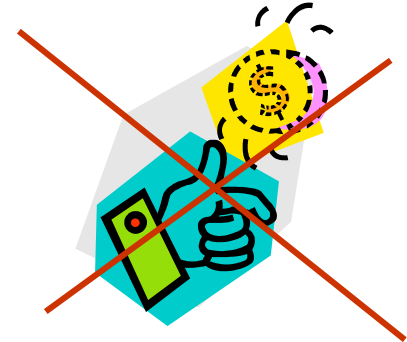


John	Bob goes <i>out</i>	Bob stays at <i>home</i>
<i>out</i>	0	1
<i>home</i>	1	0

Constrained Nash Equilibria_(1/3)

- Computing “any” Nash equilibria might not be enough
 - E.g., multi-agent planning, routing protocols, etc.
- What if we ask for “certain types of equilibrium”?
 - *Bob gets at least 1*
 - *The best social welfare*
 - *Maria cannot go to the opera*
 - ...

Bob	John goes <i>out</i>	John stays at <i>home</i>
<i>out</i>	1	0
<i>home</i>	0	1



John	Bob goes <i>out</i>	Bob stays at <i>home</i>
<i>out</i>	0	1
<i>home</i>	1	0

Constrained Nash Equilibria_(2/3)

Evaluation functions

- F_P : polynomial-time computable functions, associating real numbers with each combined strategy of players in P and their neighbors

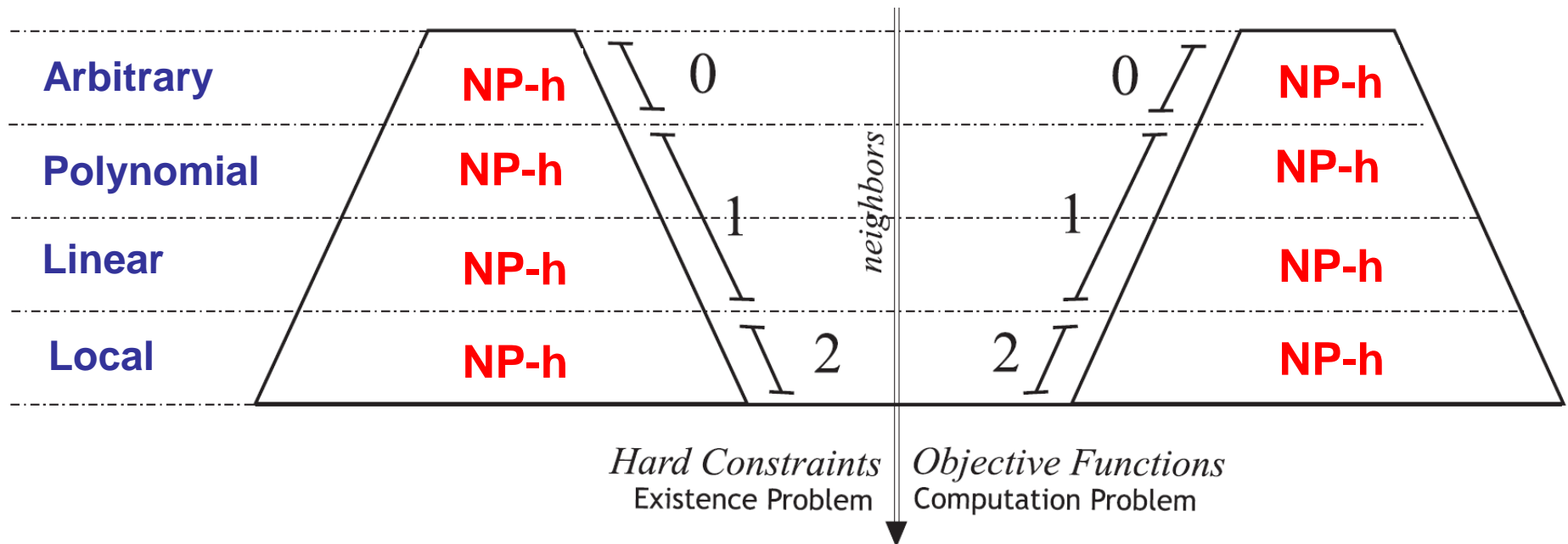
■ Examples

- Let $A_{\{G,P\}}$ return the minimum payoff between Giorgio and Paola
 - $A_{\{G,P\}} > 1$ is a guarantee for G and P
- Let $B_{\{F,P,R,G,M\}}$ return the sum of the payoffs of all players
 - By maximizing $B_{\{F,P,R,G,M\}}$, we optimize the social welfare

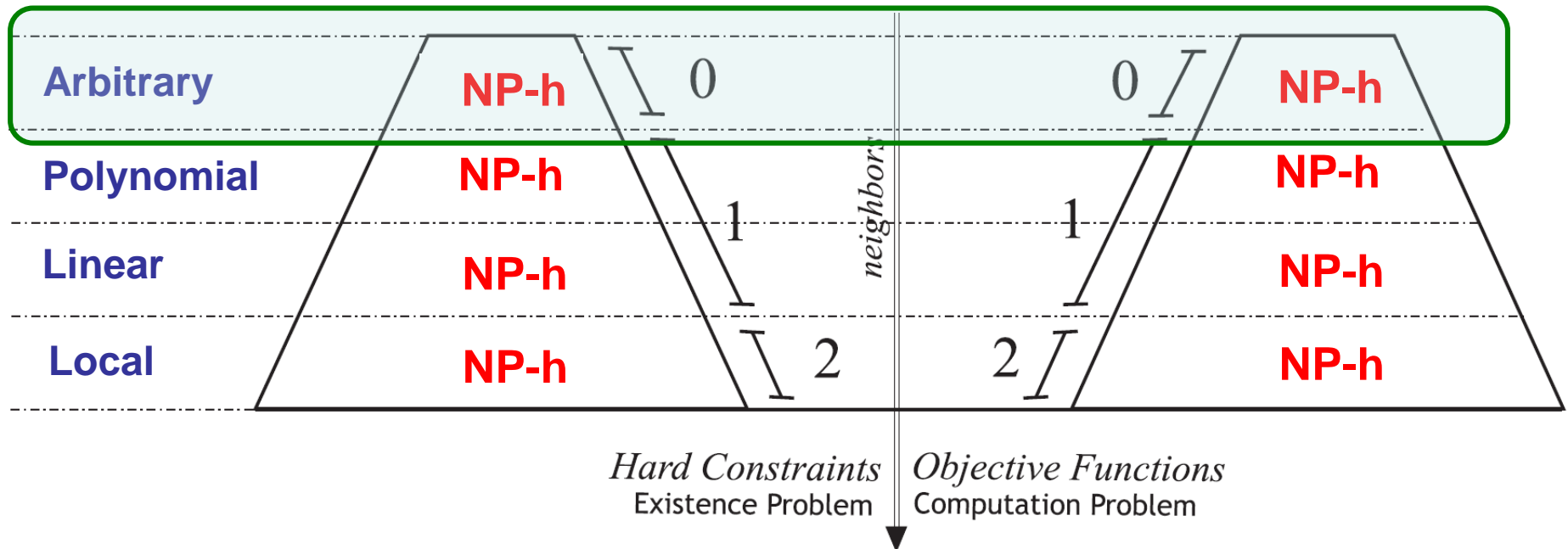
Hard Constraints

Objective Functions

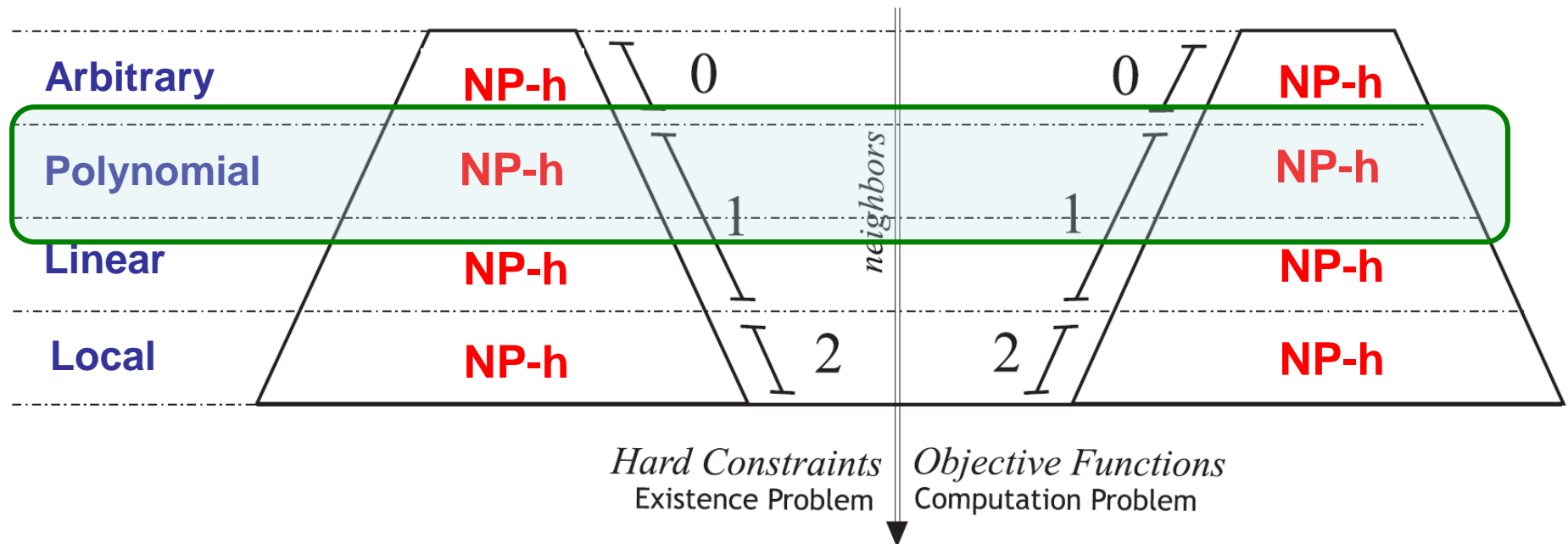
Constrained Nash Equilibria_(3/3)



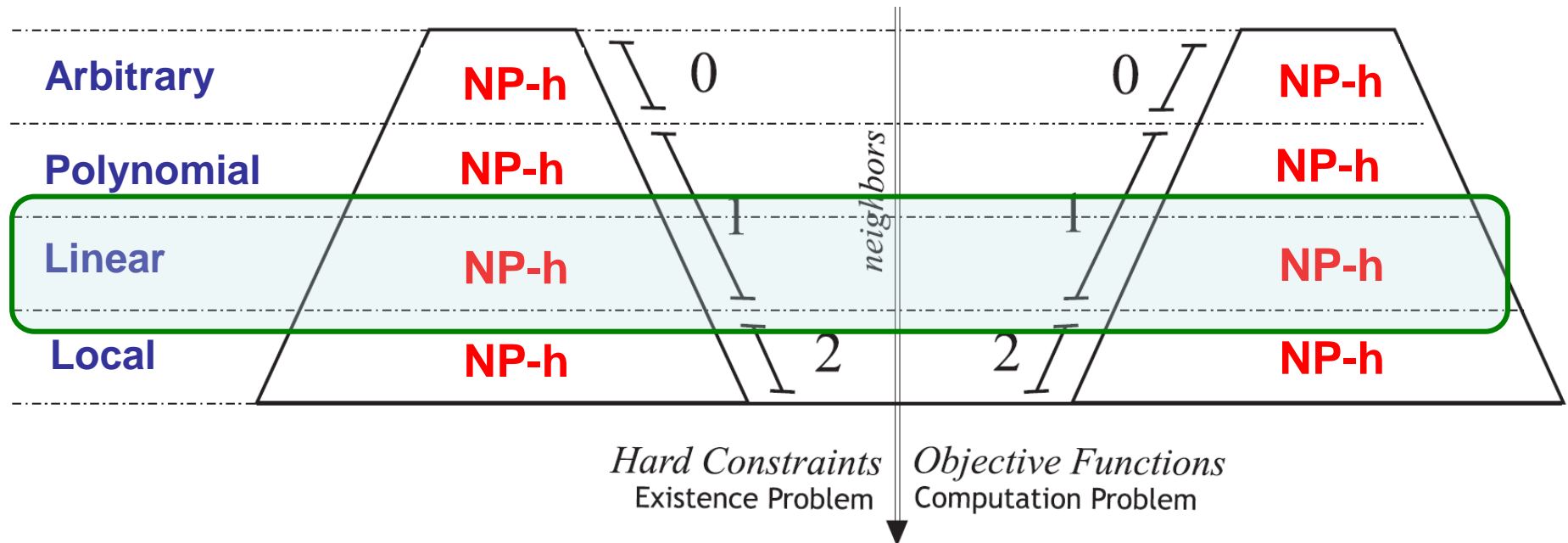
Constrained Nash Equilibria_(3/3)

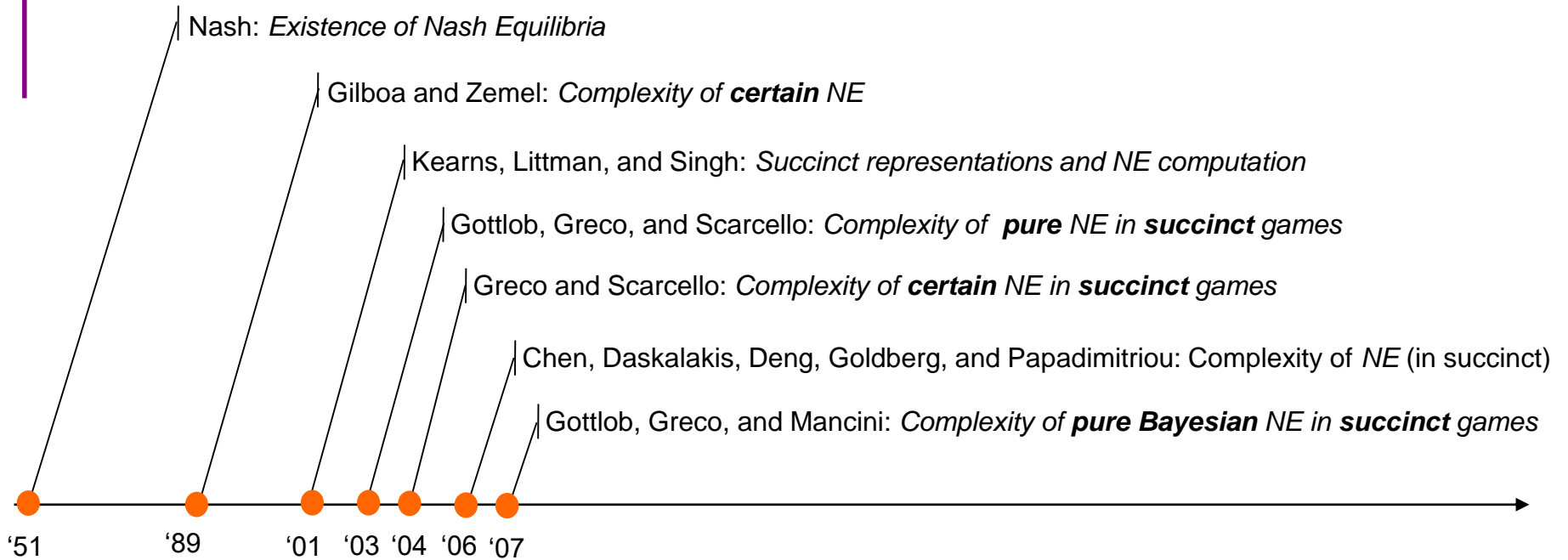


Constrained Nash Equilibria_(3/3)

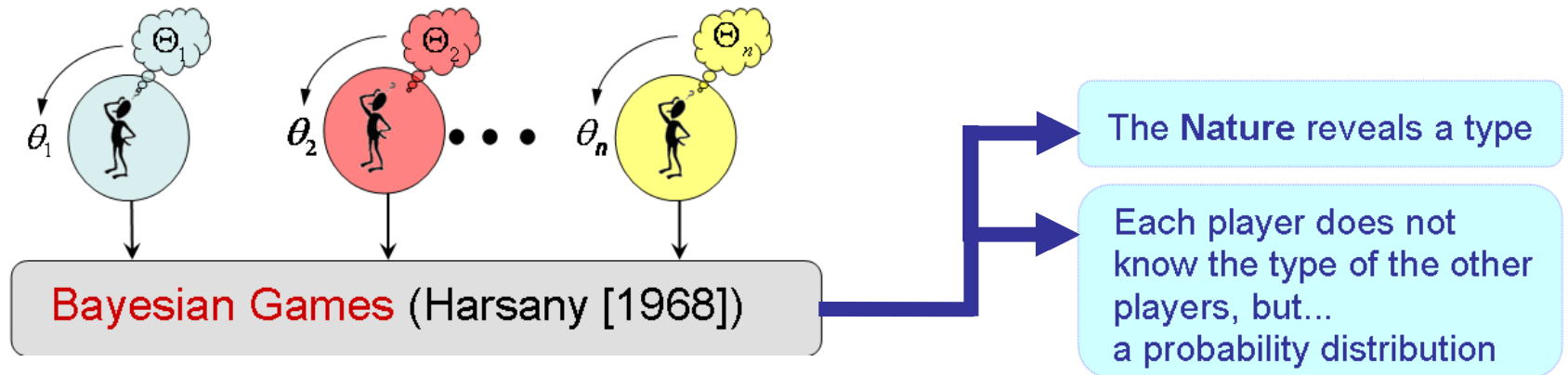


Constrained Nash Equilibria_(3/3)





Bayesian Nash Equilibria_(1/3)



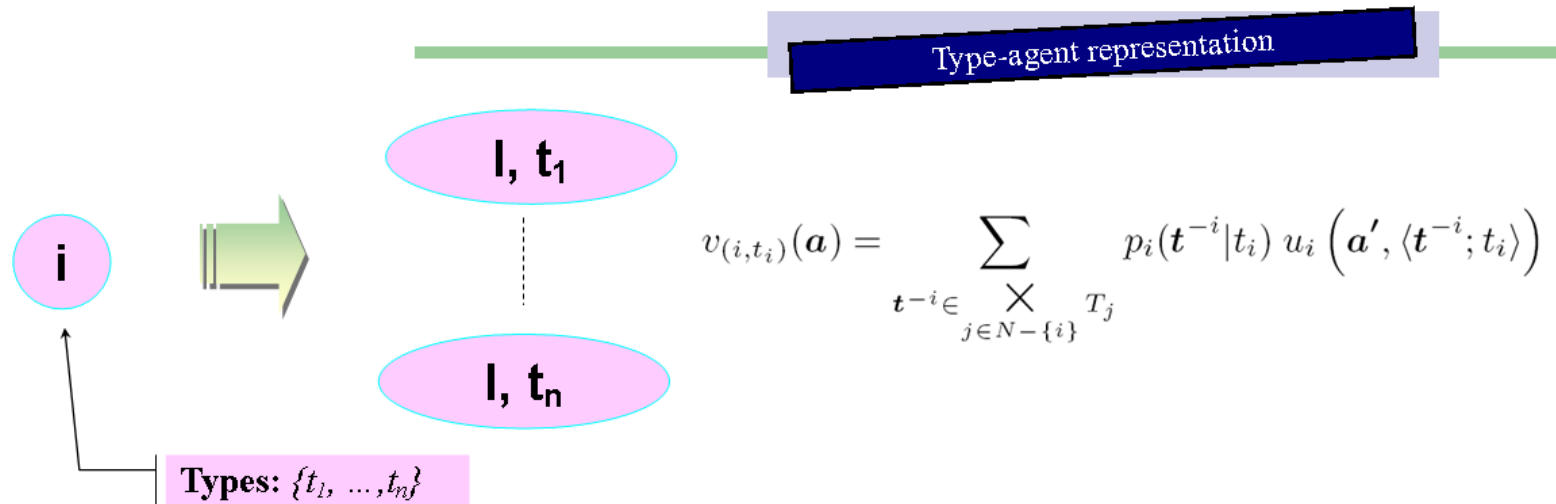
Bob	John goes <i>out</i>	John stays at <i>home</i>
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<i>home</i>	0	1

Type 1

Bob	John goes <i>out</i>	John stays at <i>home</i>
<i>out</i>	0	1
<i>home</i>	1	0

Type 2

Bayesian Nash Equilibria_(2/3)



BEs of the original game are in one-to-one correspondence with Nash Equilibria of the new game with complete information.

■ The transformation:

- ❑ Is feasible in polynomial time
- ❑ Preserves the neighborhood
- ❑ Preserves the structural properties



Easy cases are preserved

Bayesian Nash Equilibria_(3/3)

PBE is NP-complete, if the number of players is constant.

PBE is PP-hard, Hardness holds even for games where players have just two types.

PBE is PP-complete, in the fixed precision setting.

✗ PP: languages that can be decided by a nondeterministic Turing machine in polynomial time, where the acceptance condition is that a majority (more than half) of computation paths accept.



$NP \subseteq PP \subseteq PSPACE$

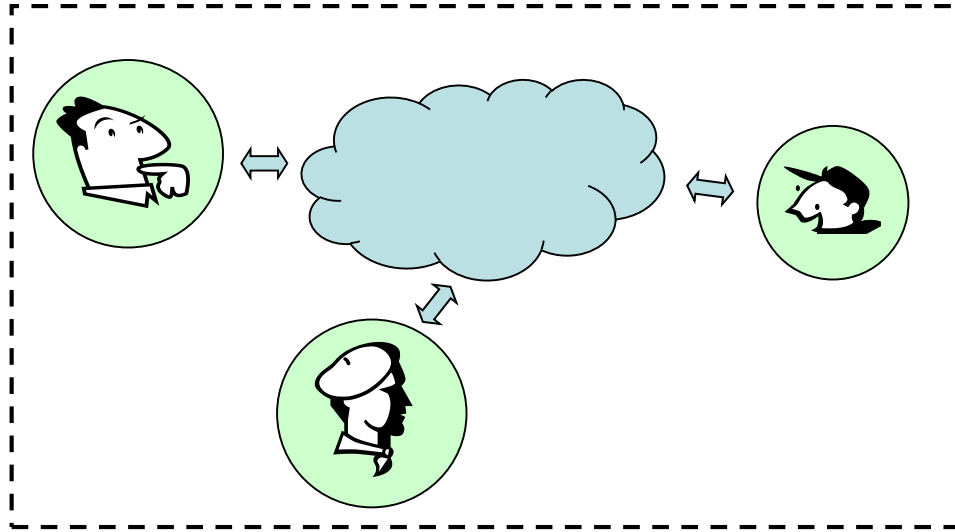
Canonical Problem: MAJ-SAT

Input: a formula Φ

Output: $true \Leftrightarrow \Phi$ is satisfied by more than half of possible assignments

Part III: Nucleolus

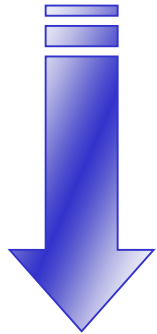
Game Theory (in a Nutshell)



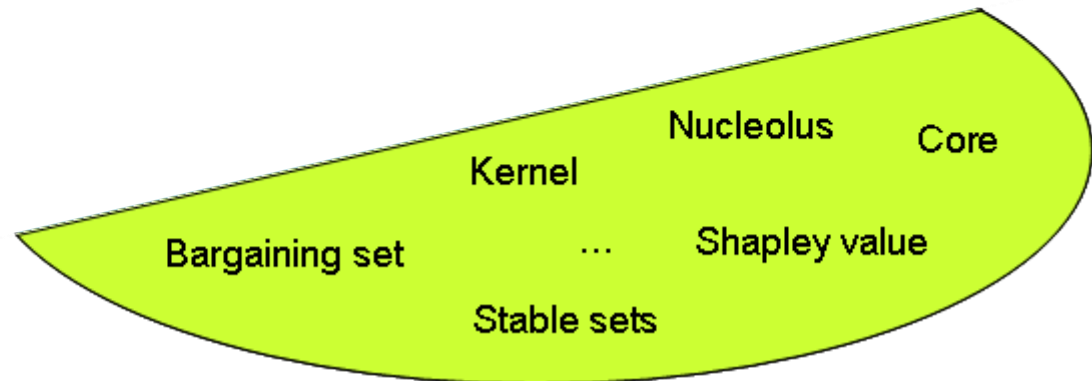
Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- Is **rational**

Which actions have to be performed?



Solution Concepts



Cooperative Game Theory_(1/2)

To perform some task
Utility distribution, if the task is performed
Jointly perform the task (with some cost)

Each player:

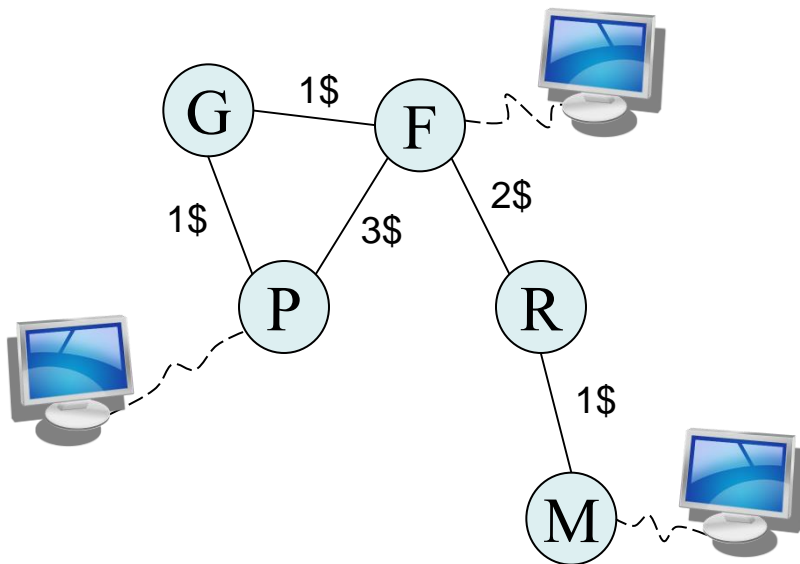
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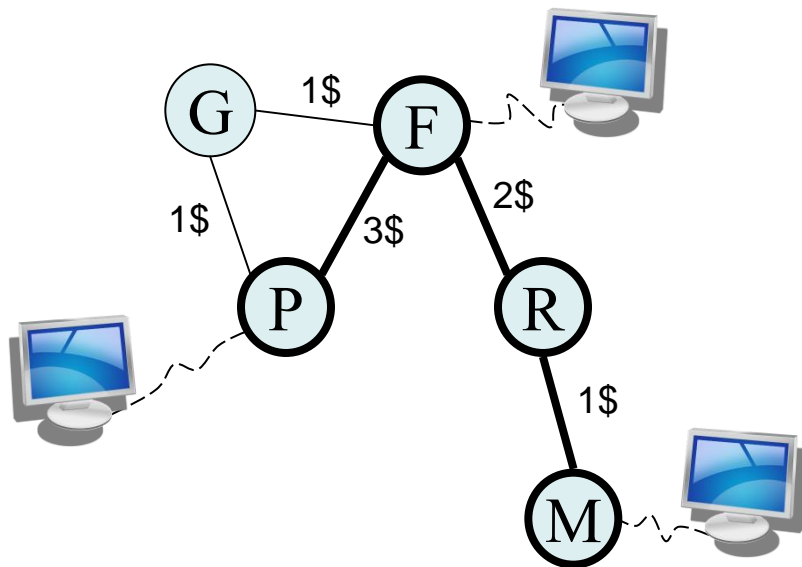
- Players get **9\$**, if they enforce connectivity
- Enforcing connectivity over an edge as a cost

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- Players get **9\$**, if they enforce connectivity
- Enforcing connectivity over an edge as a cost

Coalition {F,P,R,M} gets **9\$**, and pays **6\$**

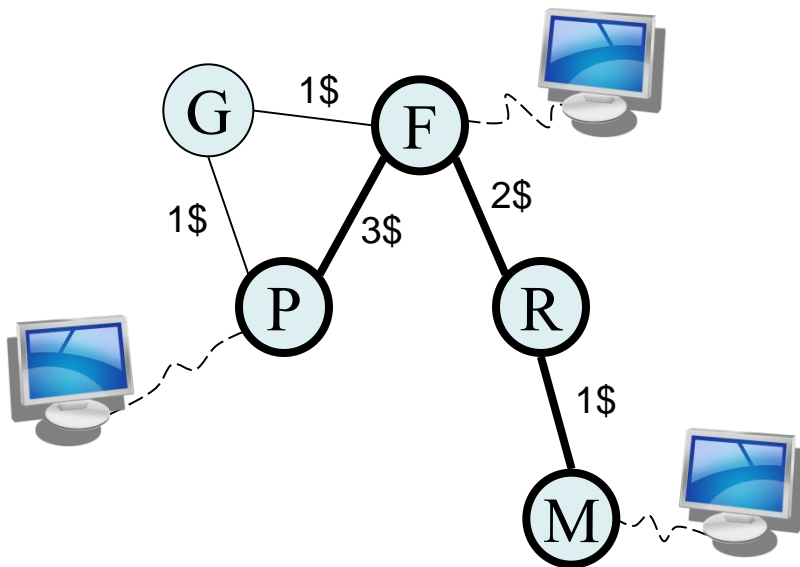
worth $v(\{F,P,R,M\}) = 9\$ - 6\$$

Cooperative Game Theory_(1/2)

To perform some task
Utility distribution, if the task is performed
Jointly perform the task (with some cost)

Each player:

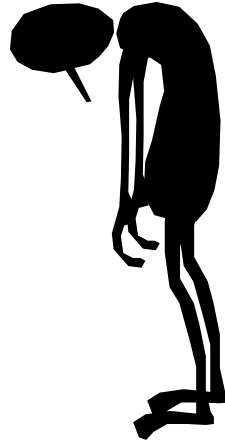
- Has a **goal** to be achieved
- Has a set of possible **actions**
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- Is rational



coalition	worth
{F}	0
...	0
{G,P,R,M}	0
{F,P,R,M}	3
{G,F,P,R,M}	4

How to distribute 9\$, based on such worths?

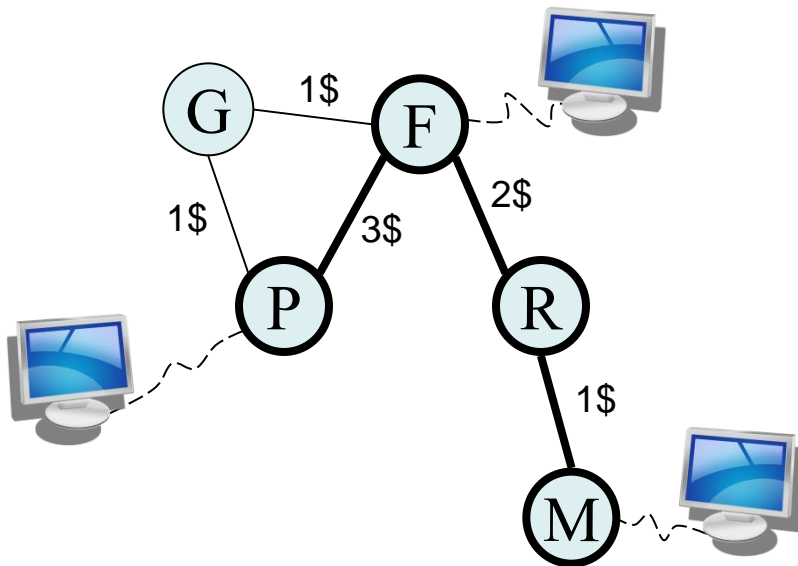
Cooperative Game Theory_(2/2)



fairness

Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- **Is rational**



coalition	worth
{F}	0
...	0
{G,P,R,M}	0
{F,P,R,M}	3
{G,F,P,R,M}	4

How to distribute 9\$, based on such worths?

The Model

- Players form *coalitions*
- Each coalition is associated with a *worth*
- A *total worth* has to be distributed

$$\mathcal{G} = \langle N, v \rangle, v : 2^N \mapsto \mathbb{R}$$

- Outcomes belong to the imputation set $X(\mathcal{G})$

$$x \in X(\mathcal{G}) \left\{ \begin{array}{l} \bullet \text{ Efficiency} \\ x(N) = v(N) \\ \bullet \text{ Individual Rationality} \\ x_i \geq v(\{i\}), \quad \forall i \in N \end{array} \right.$$

The Model

- Players form *coalitions*
- Each coalition is associated with a *worth*
- A *total worth* has to be distributed

$$\mathcal{G} = \langle N, v \rangle, v : 2^N \mapsto \mathbb{R}$$

-
- **Solution Concepts** characterize outcomes in terms of
 - Fairness
 - Stability

Excess...

- How fairness/stability can be measured?

$$e(S, x) = v(S) - x(S)$$

- The excess is a measure of the dissatisfaction of S

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$$v(\{1, 2\}) = v(\{1, 3\}) = v(\{2, 3\}) = 1$$

$$v(\{1, 2, 3\}) = 3$$

Excess...

- How fairness/stability can be measured?

$$e(S, x) = v(S) - x(S)$$

- The excess is a measure of the dissatisfaction of S

$$x = (0, 0, 3) \longrightarrow e(\{1, 2\}, x) = v(\{1, 2\}) - (x_1 + x_2) = 1 - 0 = 1$$

$$x = (1, 2, 0) \longrightarrow e(\{1, 2\}, x) = v(\{1, 2\}) - (x_1 + x_2) = 1 - 3 = -2$$

$$v(\{1\}) = v(\{2\}) = v(\{3\}) = 0$$

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...and the Nucleolus

- Arrange excess values in non-increasing order

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$$\theta(x) = (0, 0, -1, -1, -2, -2)$$

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...and the Nucleolus

- Arrange excess values in non-increasing order

Core Imputation



$$x = (1, 2, 0)$$

$$\theta(x) = (0, 0, -1, -1, -2, -2)$$

$$v(\{1\}) = v(\{2\}) = v(\{3\}) = 0$$

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...and the Nucleolus

- Arrange excess values in non-increasing order

$$x^* = (1, 1, 1)$$

$$\theta(x^*) = (-1, -1, -1, -1, -1, -1)$$

$$x = (1, 2, 0)$$

$$\theta(x) = (0, 0, -1, -1, -2, -2)$$

$$v(\{1\}) = v(\{2\}) = v(\{3\}) = 0$$

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...and the Nucleolus

- Arrange excess values in non-increasing order

Definition [Schmeidler]

The *nucleolus* $\mathcal{N}(\mathcal{G})$ of a game \mathcal{G} is the set

$$\mathcal{N}(\mathcal{G}) = \{x \in X(\mathcal{G}) \mid \nexists y \in X(\mathcal{G}) \text{ s.t. } \theta(y) \prec \theta(x)\}$$

$$x^* = (1, 1, 1)$$

$$\theta(x^*) = (-1, -1, -1, -1, -1, -1)$$

$$x = (1, 2, 0)$$

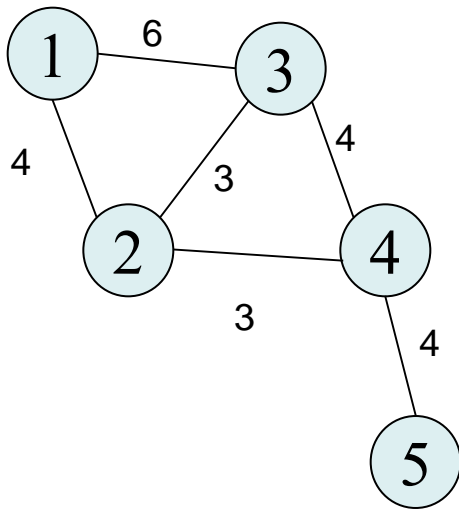
$$\theta(x) = (0, 0, -1, -1, -2, -2)$$

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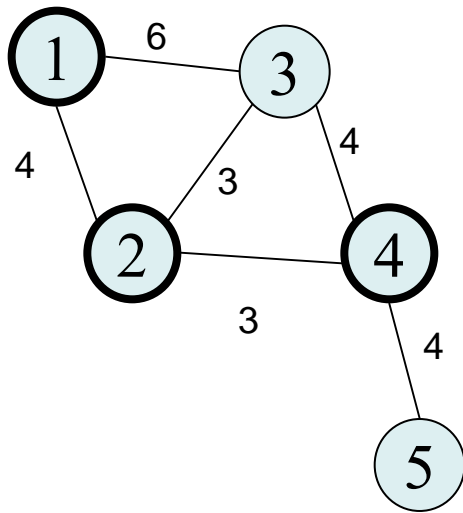
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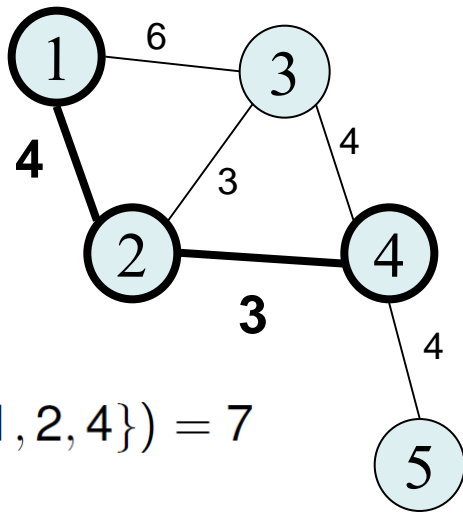
Graph Games



Graph Games

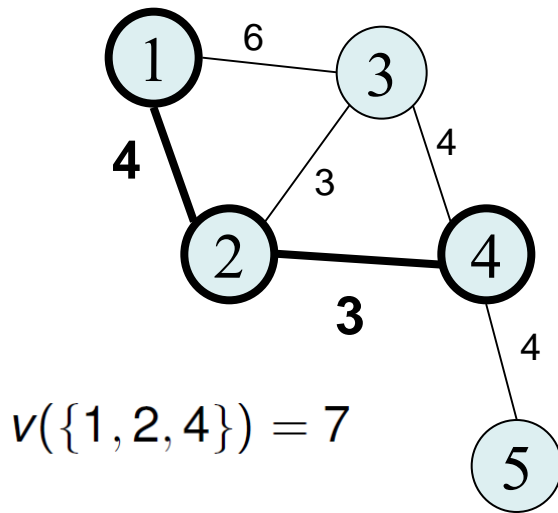


Graph Games



$$v(\{1, 2, 4\}) = 7$$

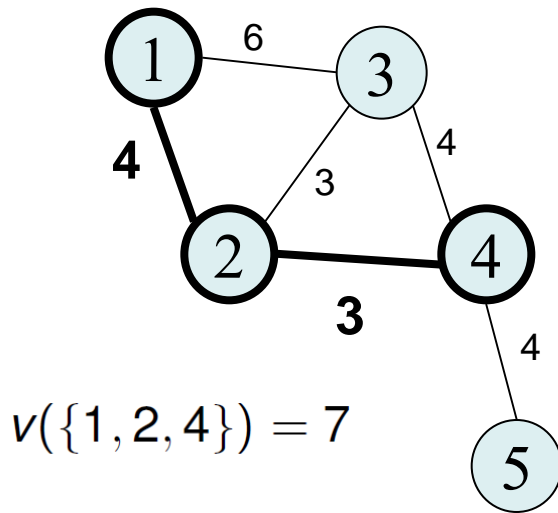
Graph Games



- *Graph Games* [Deng and Papadimitriou, 1994]
 - Computational issues of several solution concepts
 - The *(pre)nucleolus* can be computed in **P**

$$x_i^* = \frac{1}{2} \sum_{j \neq i} w_{i,j}$$

Graph Games



- *Graph Games* [Deng and Papadimitriou, 1994]
 - Computational issues of several solution concepts
 - The *(pre)nucleolus* can be computed in **P**

$$x_i^* = \frac{1}{2} \sum_{j \neq i} w_{i,j}$$

-
- *Cost allocation on trees* [Megiddo, 1978]
 - Polynomial time algorithm
 - *Flow games* [Deng, Fang, and Sun, 2006]
 - Polynomial time algorithm on simple networks (unitary edge capacity)
 - **NP**-hard, in general
 - *Weighted voting games* [Elkind and Pasechnik, 2009]
 - Pseudopolynomial algorithm

Kopelowitz, 1967

$$\text{LP}_1 \left\{ \begin{array}{l} \min \epsilon_1 \\ e(S, x) \leq \epsilon_1 \\ x \in X(\mathcal{G}) \end{array} \right. \quad \forall S \subset N, S \notin W_0 = \{\emptyset\}$$

Kopelowitz, 1967

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$$\text{LP}_2 \left\{ \begin{array}{ll} \min \epsilon_2 & \\ e(S, x) = \epsilon_1^* & \forall S \in W_1 \\ e(S, x) \leq \epsilon_2 & \forall S \subset N, S \notin (W_0 \cup W_1) \\ x \in X(\mathcal{G}) & \end{array} \right.$$

where:

- $V_1 = \{x \mid (x, \epsilon_1^*) \text{ is an optimal solution to } \text{LP}_1\}$
- $W_1 = \{S \subseteq N \mid e(S, x) = \epsilon_1^*, \text{ for every } x \in V_1\}$

Kopelowitz, 1967

$\min \epsilon_k$

$$e(S, x) = \epsilon_r^* \quad \forall S \in W_r, r \in \{1, \dots, k-1\}$$

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How many iterations?

An Example Computation

$$N = 1, \dots, n, n+1, n+2$$

$$v(N) = n+2$$

$$v(\{i\}) = 1, i \in \{1, \dots, n\}$$

$$v(\{1, \dots, n\}) = n$$

$$v(\{n+1\}) = v(\{n+2\}) = 0$$

$$v(\{n+1, n+2\}) = 2$$

$$v(S) = -\infty, |\{n+1, n+2\} \cap S| \geq 1, \\ |\{1, \dots, n\} \cap S| \geq 1, S \neq N$$

$$S_1, S_2, \dots \subset \{1, \dots, n\} \mid |S_i| > 1 \\ v(S_i) = |S_i| - 1 + 2^{-i}$$

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$$\begin{aligned} \epsilon_1^* &= 0 \\ x^* &= (1, \dots, 1, x_{n+1}^*, x_{n+2}^*) \end{aligned}$$



$$\text{LP}_1 \left\{ \begin{array}{l} \min \epsilon_1 \\ n - x(\{1, \dots, n\}) \leq \epsilon_1 \\ 2 - x_{n+1} - x_{n+2} \leq \epsilon_1 \\ x(\{1, \dots, n\}) + x_{n+1} + x_{n+2} = n+2 \\ x_i \geq 1, i \in \{1, \dots, n\} \\ \vdots \end{array} \right.$$

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$$\epsilon_1^* = 0$$

$$x^* = (1, \dots, 1, x_{n+1}^*, x_{n+2}^*)$$



The excess is constant

$$e(S_i, x^*) = v(S_i) - x^*(S_i) = -1 + 2^{-i}$$

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$$\begin{cases} e(S_i, x^*) \leq \epsilon_2 \\ \epsilon_2^* = -1 + 2^{-1} \end{cases}$$

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The excess is constant

$$e(S_i, x^*) = v(S_i) - x^*(S_i) = -1 + 2^{-i}$$

$$\left[\begin{aligned} e(S_i, x^*) &\leq \epsilon_3 \\ \epsilon_2^* = -1 + 2^{-1} &> \epsilon_3^* = -1 + 2^{-2}, \dots > \end{aligned} \right.$$

Kopelowitz, 1967

$\min \epsilon_k$

$$e(S, x) = \epsilon_r^* \quad \forall S \in W_r, r \in \{1, \dots, k-1\}$$

$$e(S, x) \leq \epsilon_k \quad \forall S \subset N, S \notin (W_0 \cup \dots \cup W_{k-1})$$

$$x \in X(\mathcal{G})$$

where:

- $V_r = \{x \mid (x, \epsilon_r^*) \text{ is an optimal solution to } \text{LP}_r\}$
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How many iterations?

Kopelowitz, 1967

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Theorem

The algorithm performs $\Omega(2^n)$ steps, in some cases.

cf. Mashler, Peleg, and Shapley, 1979

$\min \epsilon_k$

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LP_k

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$$\{S \subseteq N \mid x(S) = y(S), \forall x, y \in V_{k-1}\}$$

cf. Mashler, Peleg, and Shapley, 1979

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LP Approaches over Compact Games

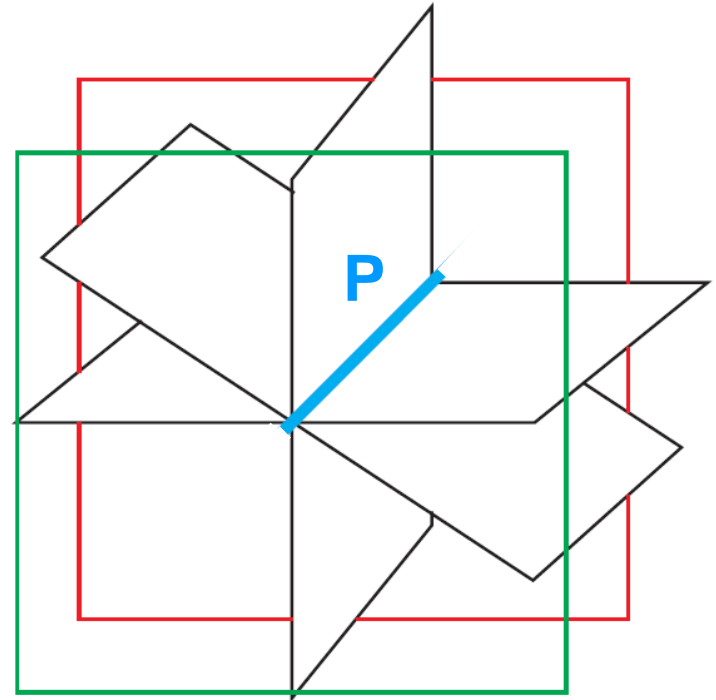
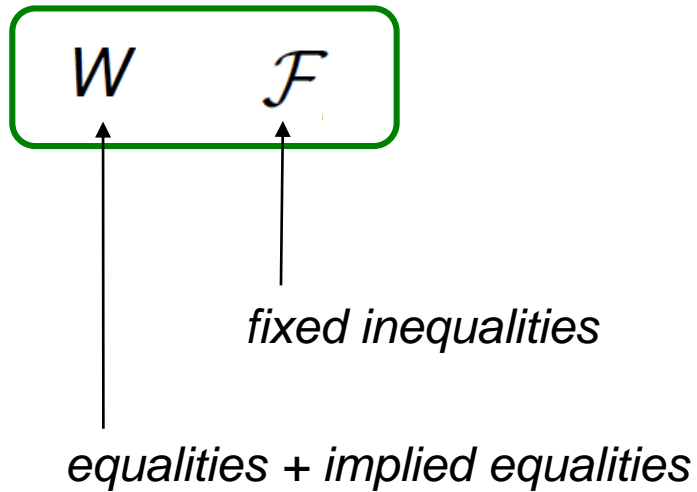
$$\text{LP}_k \left\{ \begin{array}{ll} \min \epsilon_k & \\ e(S, x) = \epsilon_r^* & \forall S \in W_r, r \in \{1, \dots, k-1\} \\ e(S, x) \leq \epsilon_k & \forall S \subset N, S \notin \mathcal{F}_{k-1} \\ x \in X(\mathcal{G}) & \end{array} \right.$$

where:

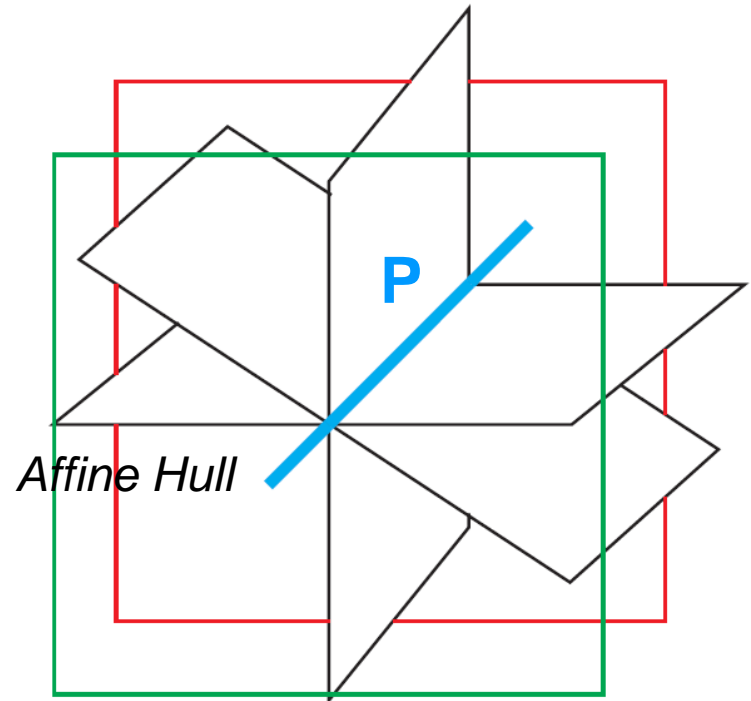
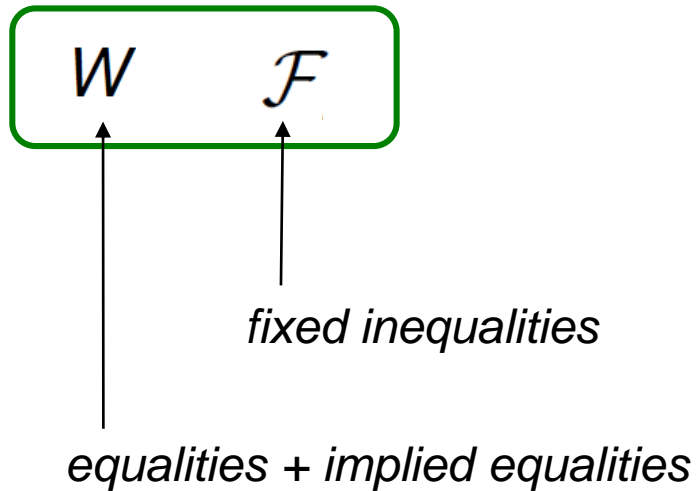
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- $\mathcal{F}_{k-1} = \{S \subseteq N \mid x(S) = y(S), \forall x, y \in V_{k-1}\}$

- In compact games, two problems have to be faced:
 - (P1) Sets W and \mathcal{F} contain exponentially many elements, but we would like to avoid listing them explicitly
 - (P2) Translate LP (complexity) results to “succinct programs”

(P1): A Convenient Representation



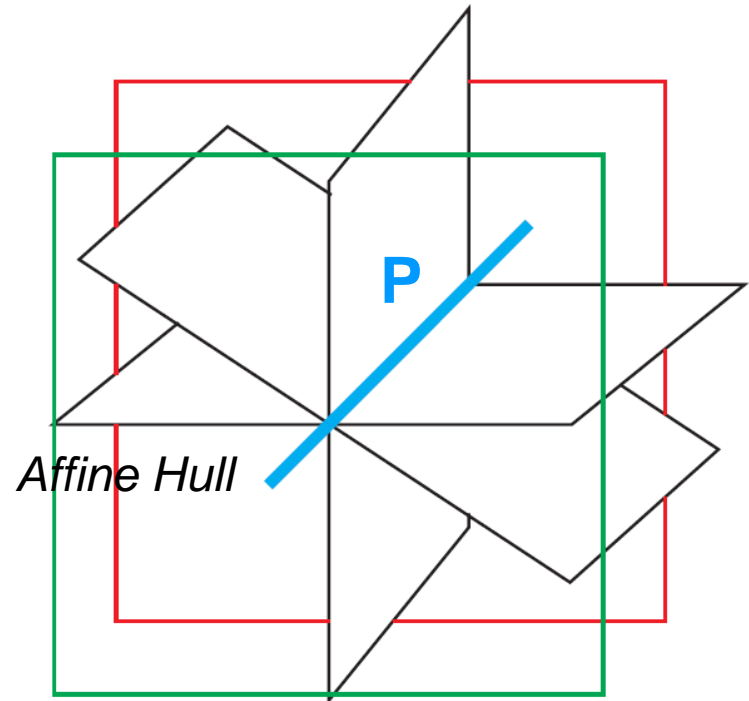
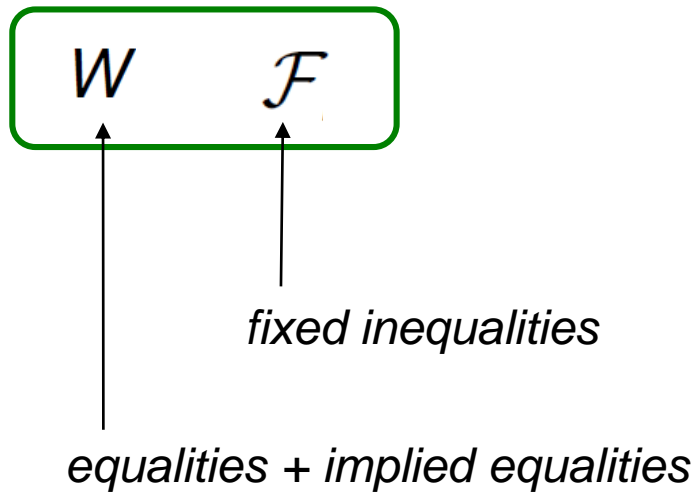
(P1): A Convenient Representation



Theorem

- $\text{aff.hull}(V_k) = \text{solutions for equalities over } W_k \cup W_{k-1} \cup \dots \cup W_1$

(P1): A Convenient Representation



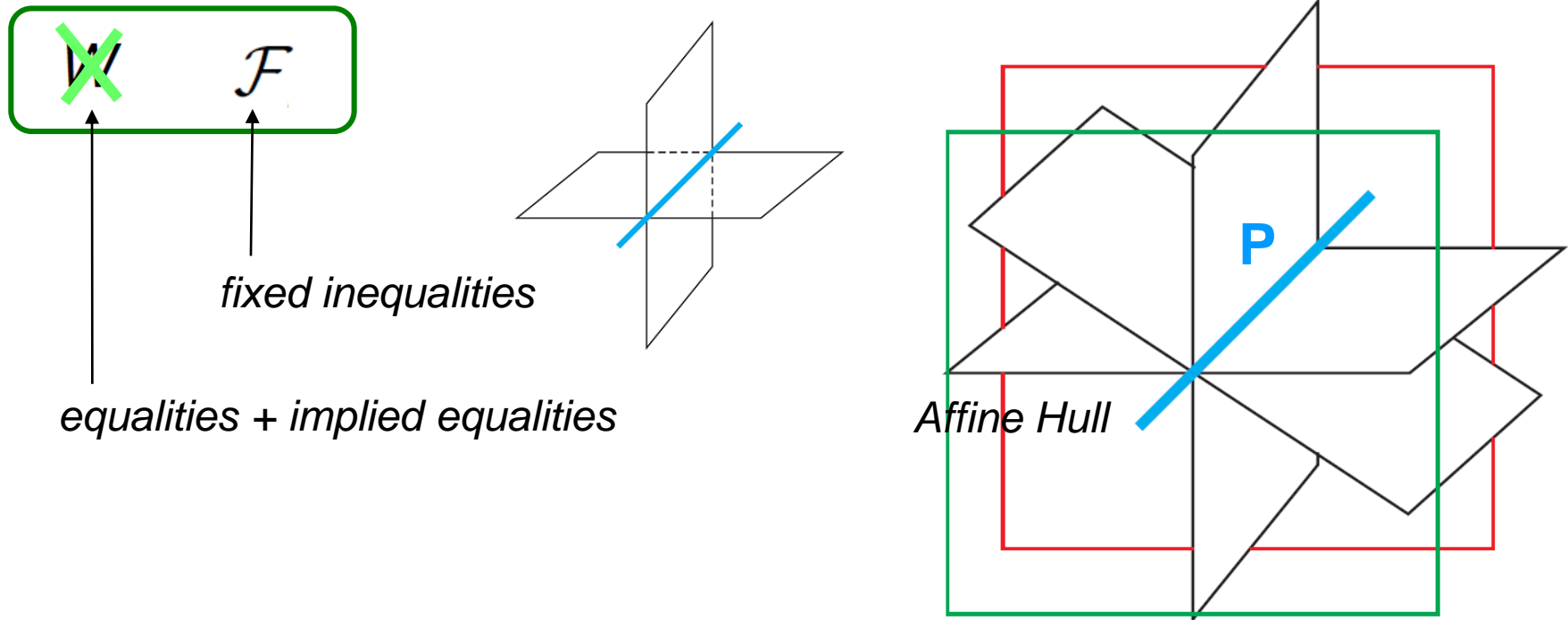
Theorem

- \bullet $\text{aff.hull}(V_k) = \text{solutions for equalities over } W_k \cup W_{k-1} \cup \dots \cup W_1$
 $\{S \subseteq N \mid e(S, x) = \epsilon_k^*, \text{ for every } x \in V_k\}$

\uparrow
 Implied equalities

$\underbrace{\hspace{10em}}$
 equalities

(P1): A Convenient Representation



Theorem

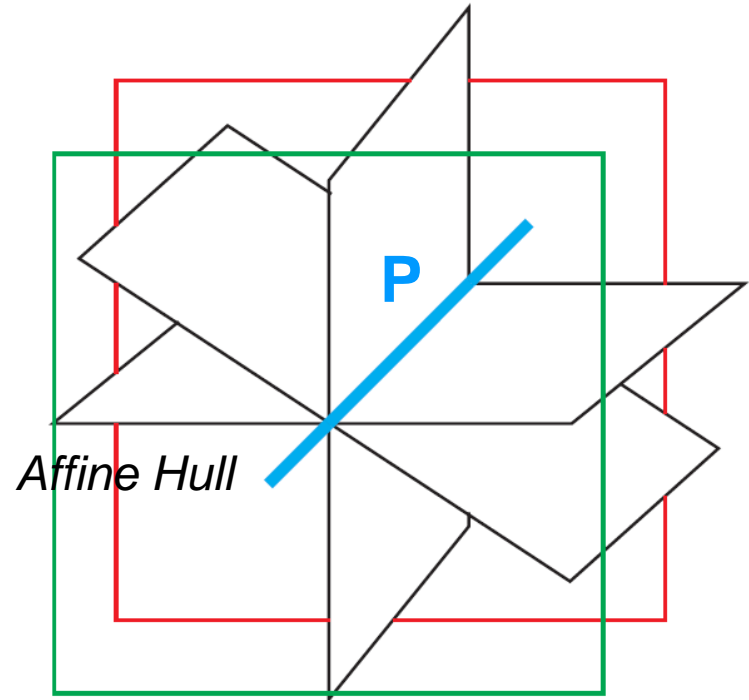
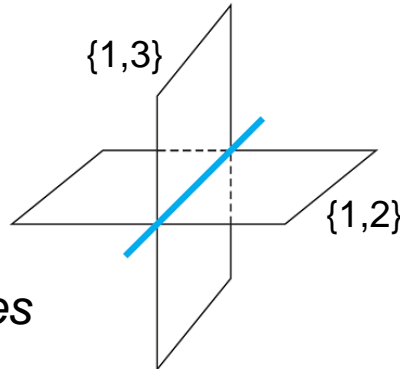
- $\text{aff.hull}(V_k) = \text{solutions for equalities over } W_k \cup W_{k-1} \cup \dots \cup W_1$
- A basis \mathcal{B}_k for $\text{aff.hull}(V_k)$ contains n vectors at most

(P1): A Convenient Representation



equalities + implied equalities

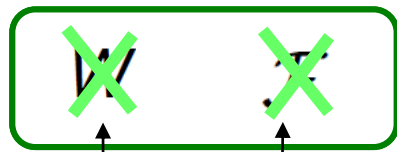
fixed inequalities



Theorem

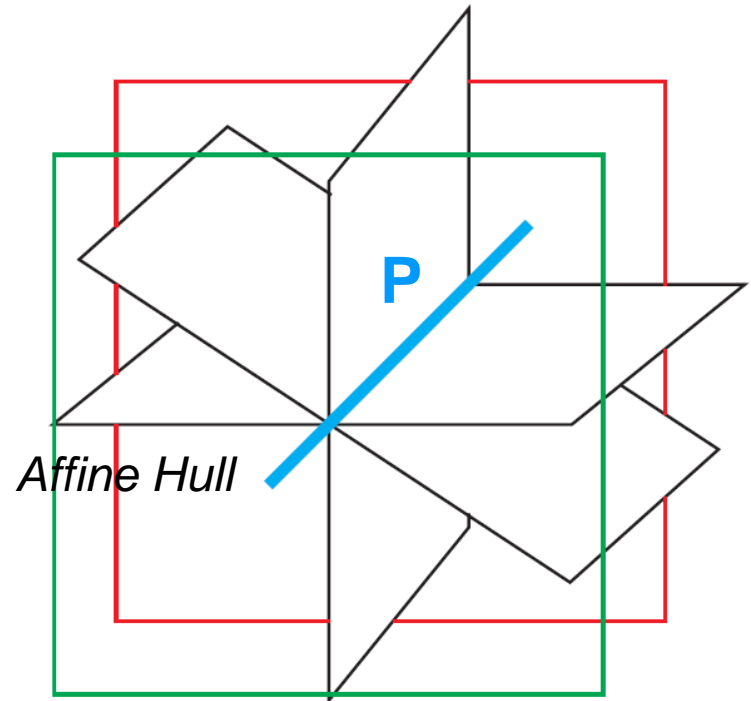
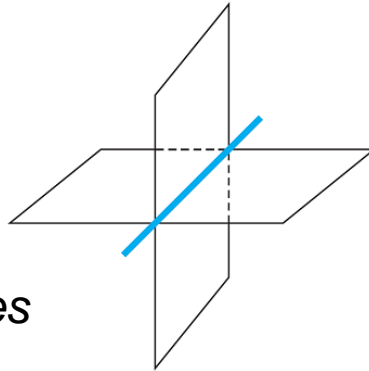
- $\text{aff.hull}(V_k) = \text{solutions for equalities over } W_k \cup W_{k-1} \cup \dots \cup W_1$
- A basis \mathcal{B}_k for $\text{aff.hull}(V_k)$ contains n vectors at most
- $S \in \mathcal{F}_k$ iff S is a linear combination of the indicator vectors for \mathcal{B}_k

(P1): A Convenient Representation



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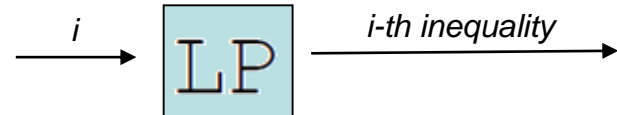
$$v : 2^N \mapsto \mathbb{R}$$

+

aff.hull



LP_{k+1}



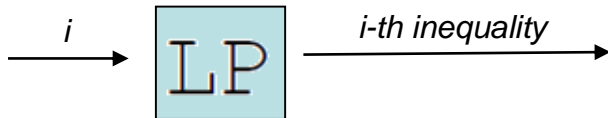
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(P2) Computation Problems

- In compact games, two problems have to be faced:
 - (P1) Sets W and \mathcal{F} contain exponentially many elements, but we would like to avoid listing them explicitly
 - (P2) Translate LP (complexity) results to “succinct programs”

(P2) Computation Problems



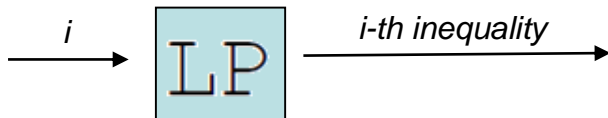
Problem	Result
MEMBERSHIP	in co-NP
NONEMPTYNESS	in co-NP
DIMENSION	in NP
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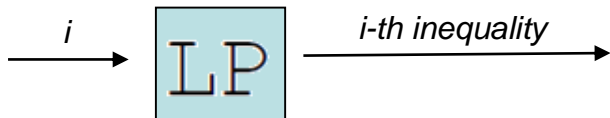
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Complexity Results



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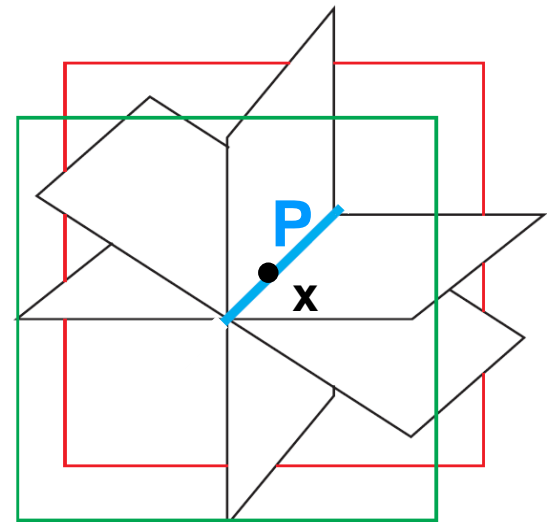
Complexity Results



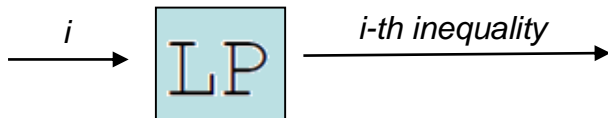
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Trivial

- Given a vector \mathbf{x} , we can:
 - Guess an index i
 - Check that the i -th inequality is not satisfied by \mathbf{x}

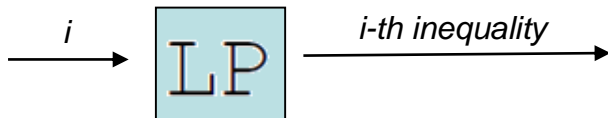


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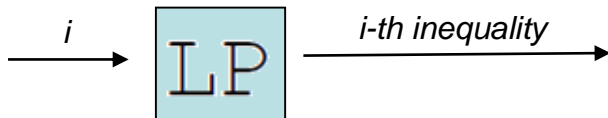


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Proof

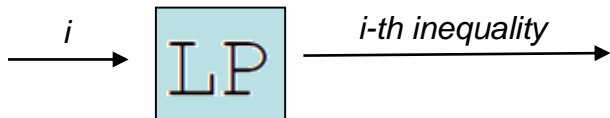
- By **Helly's theorem**, we can solve the complementary problem in **NP**:
 - Guess $n+1$ inequalities
 - Check that they are not satisfiable (in polynomial time)

Complexity Results



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Complexity Results

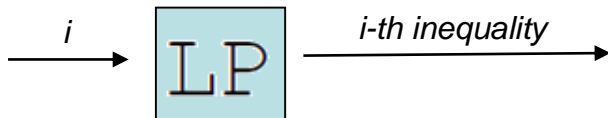


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Proof Overview

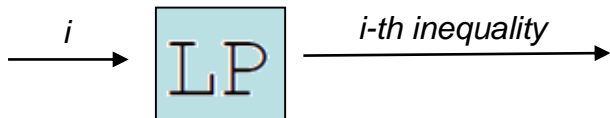
- (1) The dimension is $n-k$ at most, if there are at least k linear independent implied equalities
 - (2) In order to check that the i -th inequality is an implied one, we can guess in **NP** a **support set** $W(i)$, again by Helly's theorem:
 - n inequalities + the i -th inequality treated as strict
 - $W(i)$ is not satisfiable, which can be checked in polynomial time
- Guess k implied equalities plus their support sets
 - Check that they are linear independent

Complexity Results



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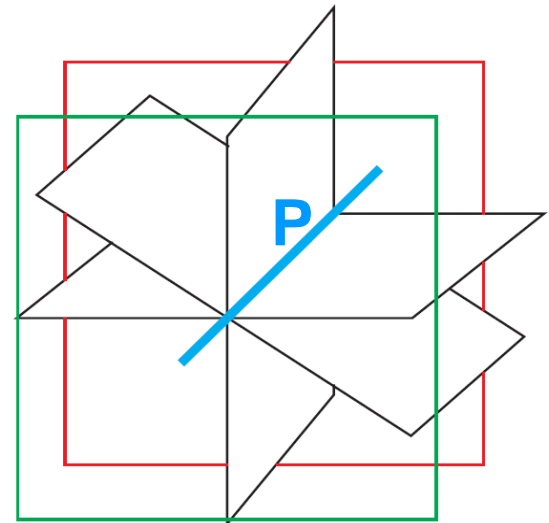
Complexity Results



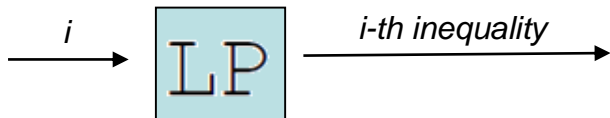
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Proof

- (1) Compute the dimension $\mathbf{n-k}$, with a *binary search* invoking an **NP** oracle
- (2) Guess \mathbf{k} implied equalities plus their support sets

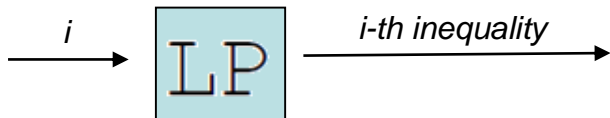


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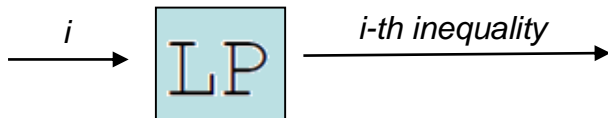


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Routine

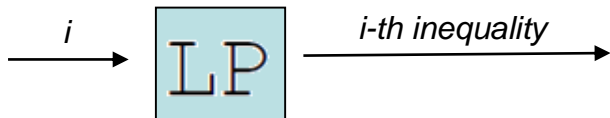
- (1) Bfs can be represented with polynomially many bits
- (2) LP induces a polytope and hence the optimum is achieved on some bfs.
- (3) Perform a *binary search* over the range of the optimum solution:
 - Add the current value as a constraint, and check satisfiability

Complexity Results



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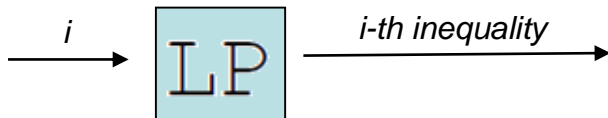


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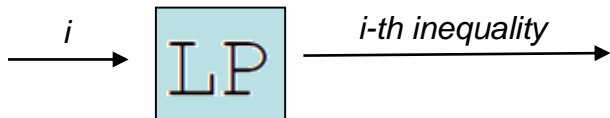
- LP induces a polytope
- Compute the lexicographically maximum bfs solution, by iterating over the various components, and treating each of them as an objective function to be optimized.

Complexity Results



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Routine

- (1) Compute the optimum value
- (2) Define LP' as LP plus the constraint stating that the objective function must equal the optimum value
- (3) Compute a feasible value for LP'

Putting It All Together

$$\begin{array}{l} \text{LP}_k \\ \left\{ \begin{array}{ll} \min \epsilon_k & \\ e(S, x) = \epsilon_r^* & \forall S \in W_r, r \in \{1, \dots, k-1\} \\ e(S, x) \leq \epsilon_k & \forall S \subset N, S \notin \mathcal{F}_{k-1} \\ x \in X(\mathcal{G}) & \end{array} \right. \end{array}$$

where:

- $V_r = \{x \mid (x, \epsilon_r^*) \text{ is an optimal solution to } \text{LP}_r\}$
- $W_r = \{S \subseteq N \mid e(S, x) = \epsilon_r^*, \text{ for every } x \in V_r\}$
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M.P.S.

$$v : 2^N \mapsto \mathbb{R}$$

$\begin{array}{c} + \\ \text{aff.hull} \end{array} \longrightarrow \text{LP}_{k+1}$

Compact Encoding

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Algorithms in $\mathbf{F}\Delta_2^P$

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Algorithms in $\mathbf{F}\Delta_2^P$

Theorem

Computing the nucleolus is feasible in $\mathbf{F}\Delta_2^P$. Thus, deciding whether an imputation is the nucleolus is feasible in Δ_2^P .

Checking Problem

Theorem

*Deciding whether an imputation is the nucleolus is Δ_2^P -hard.
Thus, it is Δ_2^P -complete.*

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Proof (Reduction for Graph Games: *The cost of individual rationality!*)

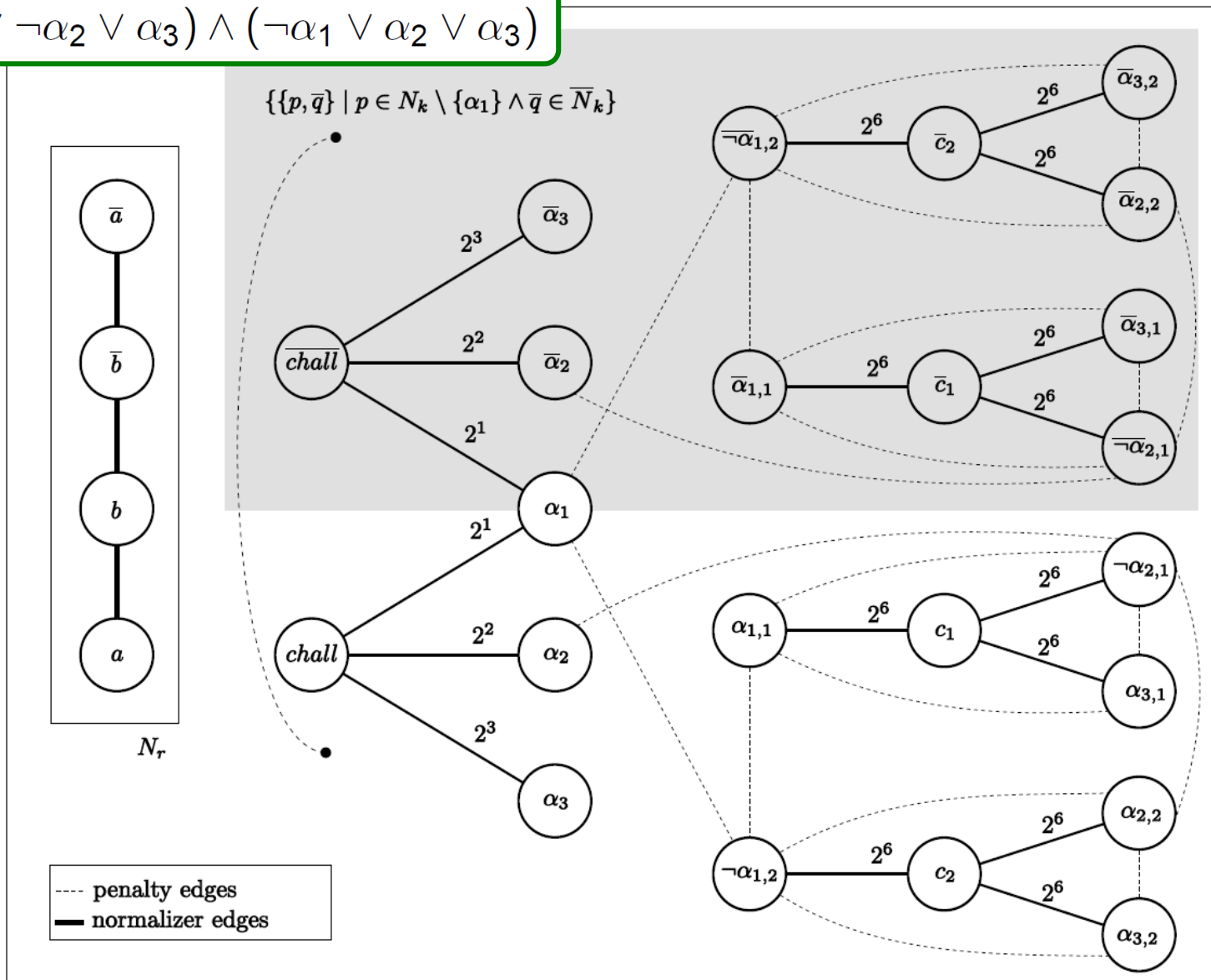
- Deciding the truth value of the least significant variable in the lexicographically maximum satisfying assignment

$$\hat{\phi} = (\alpha_1 \vee \neg\alpha_2 \vee \alpha_3) \wedge (\neg\alpha_1 \vee \alpha_2 \vee \alpha_3)$$

$$\alpha_1 < \alpha_2 < \alpha_3$$

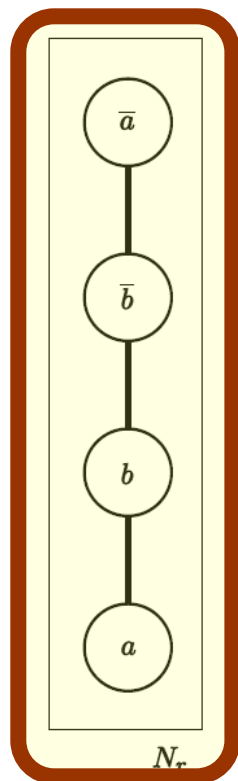
Overview of the Reduction

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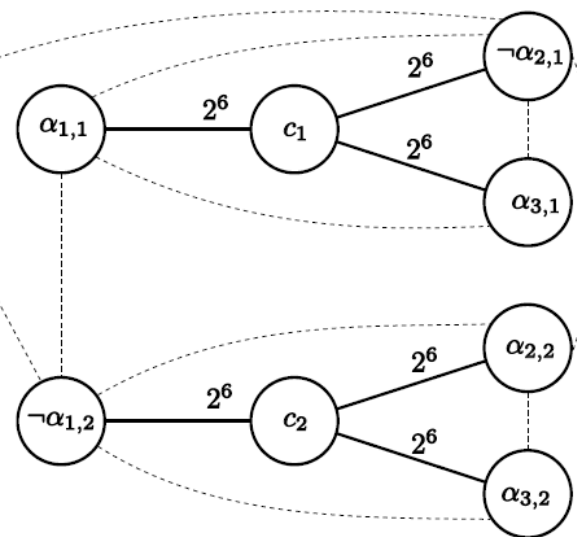
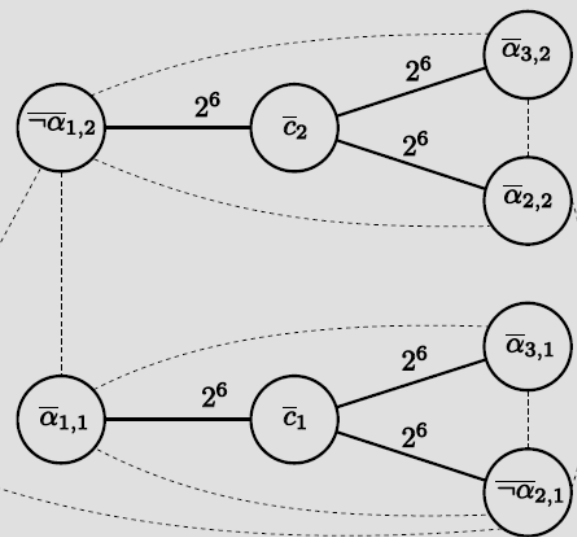
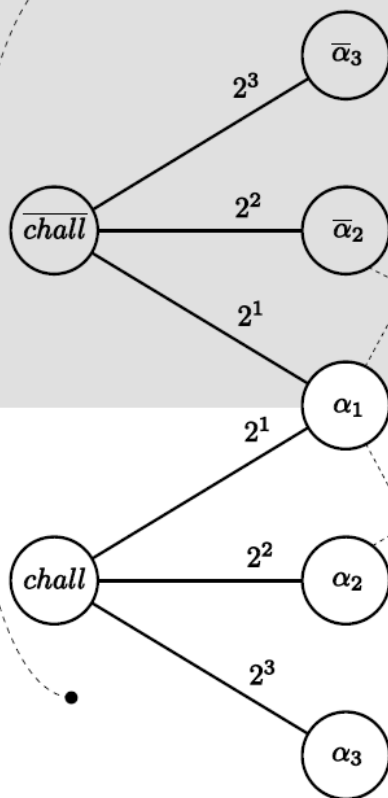


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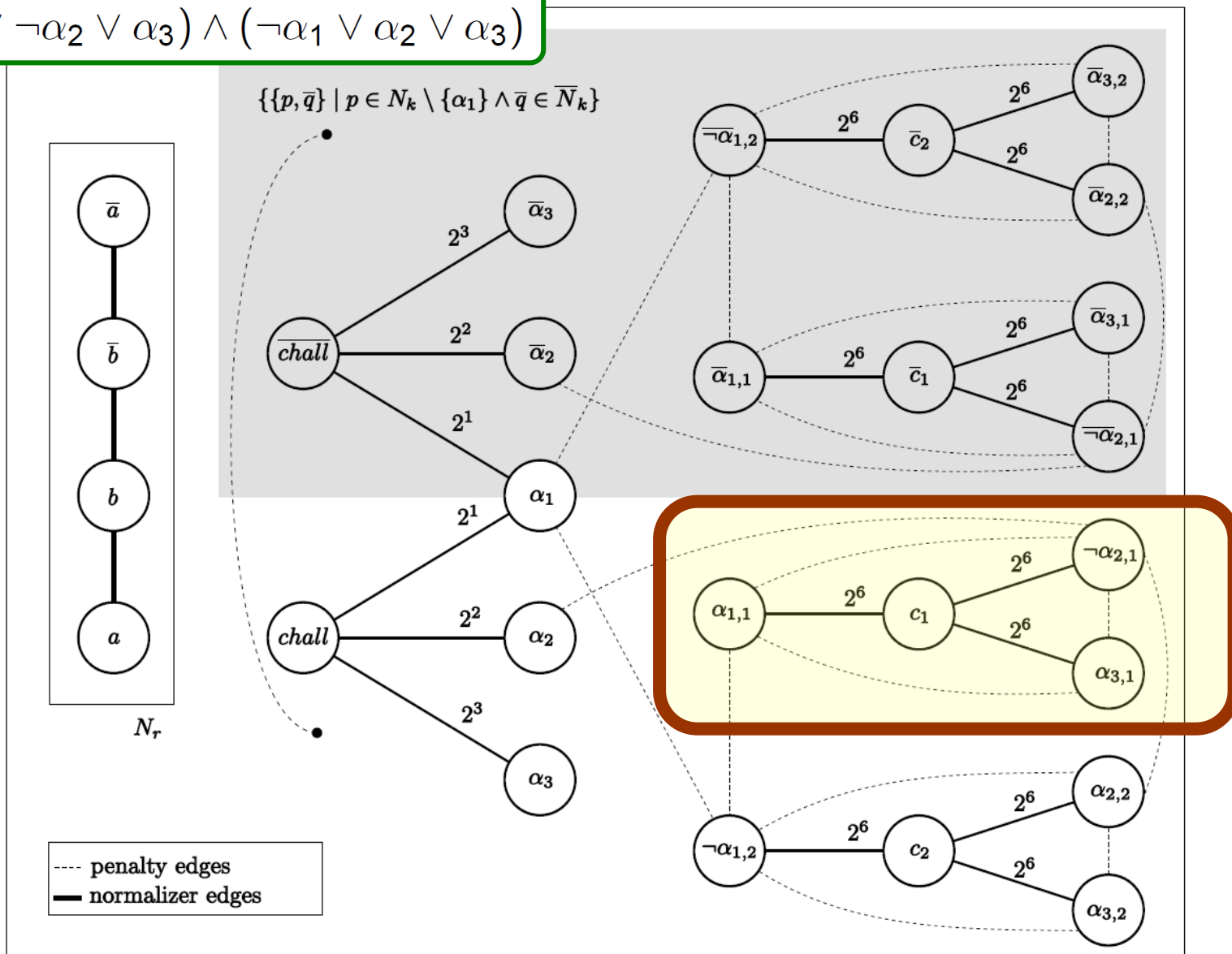
$$\{\{p, \bar{q}\} \mid p \in N_k \setminus \{\alpha_1\} \wedge \bar{q} \in \bar{N}_k\}$$



--- penalty edges
— normalizer edges

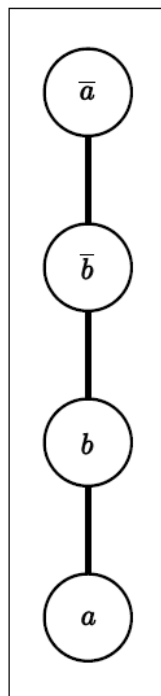
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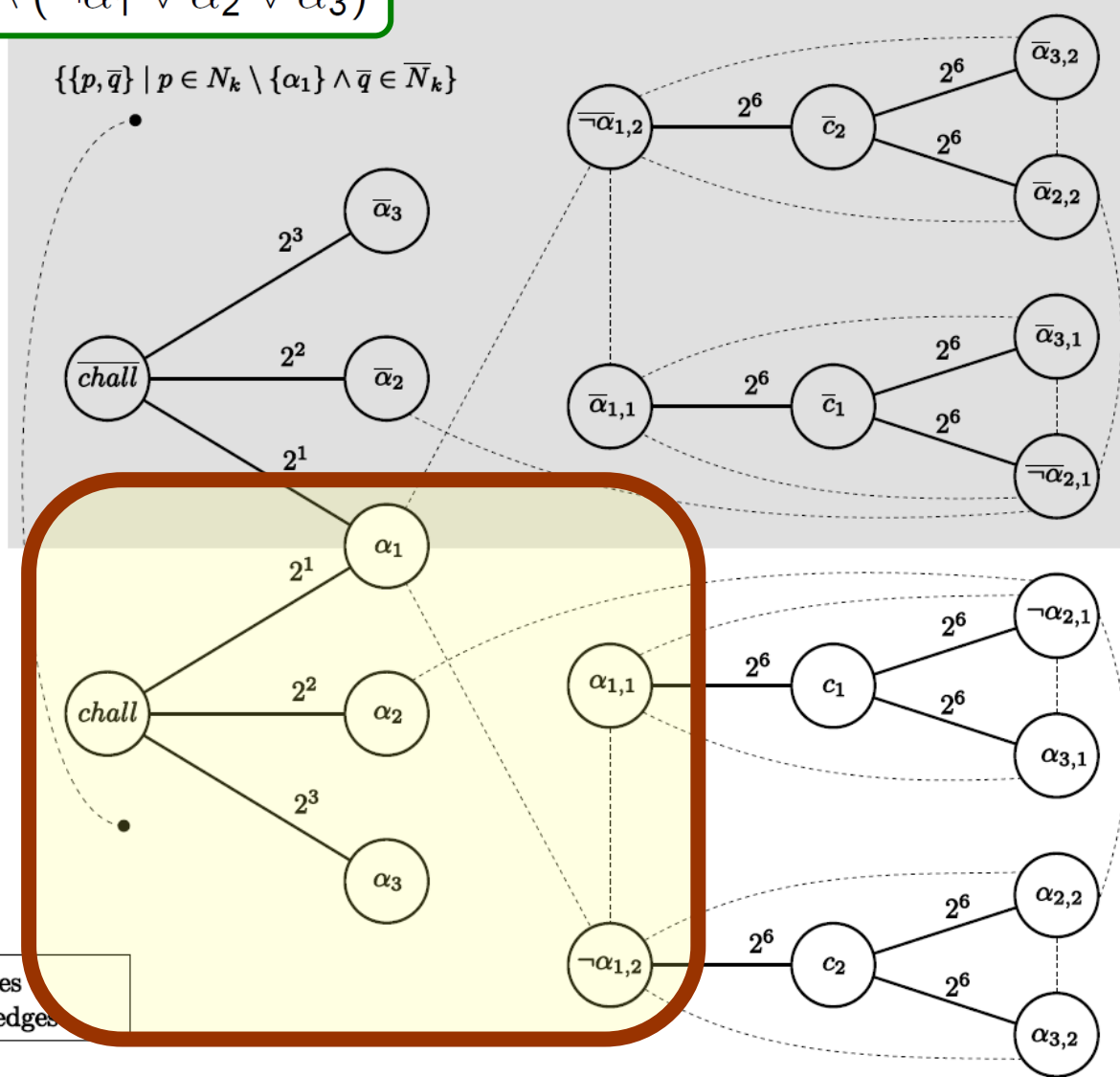
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N_r

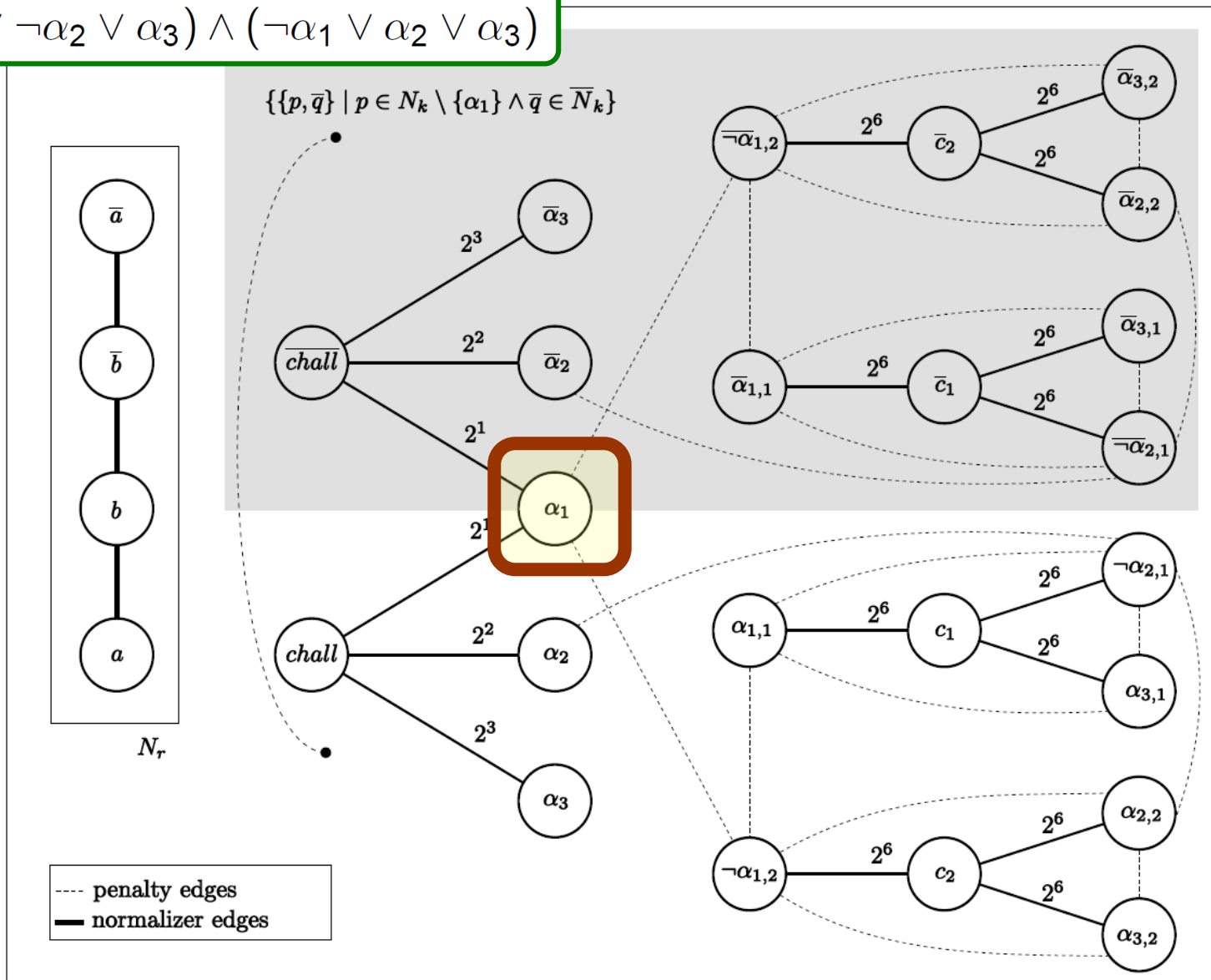
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Thank you!
