

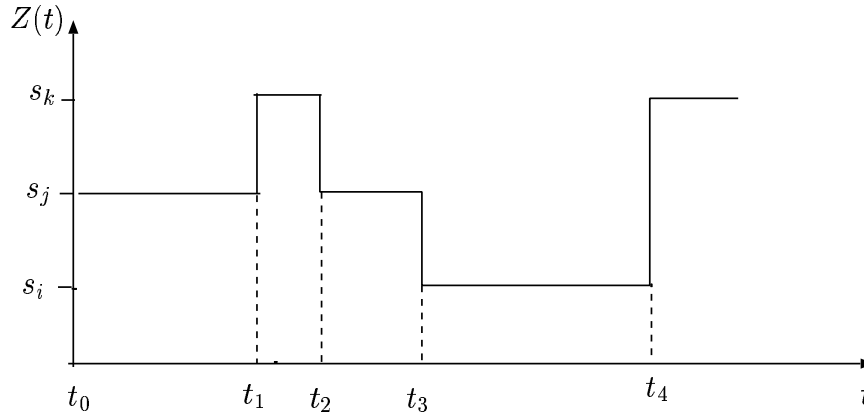
CONTINUOUS-TIME MARKOV CHAINS

Andrea Bobbio

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Continuous Time Markov Process

A stochastic process $Z(t)$ defined over a discrete state space S of cardinality N is a continuous-time discrete-state Markov process (or Markov chain - CTMC) if:



for any sequence

$$(0 < t_1 < t_2 < \dots < t_{m-1} < t_m)$$

The following property holds:

$$\begin{aligned} Pr \{ Z(t_m) = s_{j_m} | Z(t_{m-1}) = s_{j_{m-1}}, \dots, Z(t_1) = s_{j_1} \} \\ = Pr \{ Z(t_m) = s_{j_m} | Z(t_{m-1}) = s_{j_{m-1}} \} \end{aligned}$$

Transition Probability Matrix

Let us introduce the following notation:

$$p_{ij}(u, x) = \Pr \{ Z(x) = s_j | Z(u) = s_i \} \quad (u \leq x)$$

With:

$$p_{ii}(x, x) = 1 \quad ; \quad p_{ij}(x, x) = 0$$

$p_{ij}(u, x)$ is the conditional probability of transition in state s_j at time x given the process was in state s_i at time u .

$$p_i(x) = \Pr \{ Z(x) = s_i \}$$

$p_i(x)$ is the probability that the process is in state s_i at time x and is called the occupancy state probability or simply *state probability*.

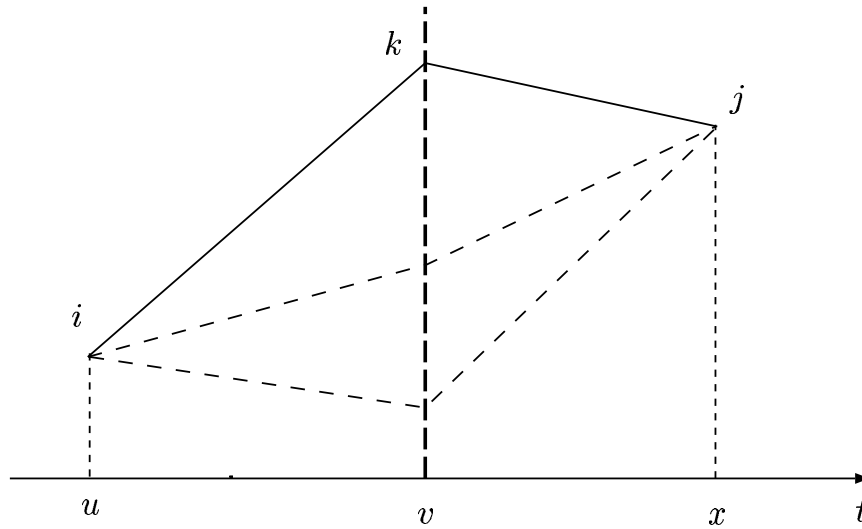
From the above definitions:

$$\sum_{j=1}^N p_{ij}(u, x) = 1 \quad ; \quad \sum_{i=1}^N p_i(x) = 1$$

Chapman-Kolmogorov Equations

The Markov property implies the following Chapman-Kolmogorov equations:

$$\begin{aligned}
 p_j(x) &= \sum_i p_i(u) \cdot p_{ij}(u, x) \\
 p_{ij}(u, x) &= \sum_k p_{ik}(u, v) \cdot p_{kj}(v, x) \quad \text{for } u \leq v \leq x
 \end{aligned}$$



Let $\mathbf{P}(u, x) = [p_{ij}(u, x)]$ be the $(N \times N)$ square transition probability matrix.

Let $\mathbf{p}(x) = [p_i(x)]$ be the (N) -dimensional row vector of the state probabilities.

Using matrix algebra, the C-K equations can be written as:

$$\begin{aligned}
 \mathbf{p}(x) &= \mathbf{p}(u) \cdot \mathbf{P}(u, x) \\
 \mathbf{P}(u, x) &= \mathbf{P}(u, v) \cdot \mathbf{P}(v, x) \\
 \mathbf{P}(x, x) &= \mathbf{I}
 \end{aligned}$$

where \mathbf{I} is the identity matrix.

Time-Homogeneous CTMC

A CTMC is said to be time-homogeneous (or simply homogeneous), when the transition probability matrix $\mathbf{P}(u, x)$ depends only on the difference $(x - u)$.

Substituting: $x - v = t$ e $v - u = \theta$ the C-K equations become:

$$\mathbf{P}(t + \theta) = \mathbf{P}(t) \cdot \mathbf{P}(\theta) \quad ; \quad \mathbf{P}(0) = \mathbf{I}$$

Define (for $i \neq j$ and for $\Delta t \geq 0$):

$$q_{ij} = \left. \frac{dp_{ij}(t)}{dt} \right|_{t=0} = \lim_{\Delta t \rightarrow 0} \frac{p_{ij}(\Delta t) - p_{ij}(0)}{\Delta t} = \lim_{\Delta t \rightarrow 0} \frac{p_{ij}(\Delta t)}{\Delta t}$$

From the above we get:

$$q_{ij} \geq 0$$

$$p_{ij}(\Delta t) = Pr \{ Z(t + \Delta t) = j \mid Z(t) = i \} = q_{ij} \Delta t + O(\Delta t)$$

Define (for $i = j$ and for $\Delta t \geq 0$):

$$q_{ii} = \left. \frac{dp_{ii}(t)}{dt} \right|_{t=0} = \lim_{\Delta t \rightarrow 0} \frac{p_{ii}(\Delta t) - p_{ii}(0)}{\Delta t} = - \lim_{\Delta t \rightarrow 0} \frac{1 - p_{ii}(\Delta t)}{\Delta t}$$

From the above we get:

$$q_{ii} < 0$$

$$p_{ii}(\Delta t) = Pr \{ Z(t + \Delta t) = i \mid Z(t) = i \} = 1 + q_{ii} \Delta t + O(\Delta t)$$

CK Equations for Time-Homogeneous CTMC

q_{ij} are the transition rates, whose physical interpretation is:

$$p_{ij}(\Delta t) = \Pr \{ Z(t + \Delta t) = j \mid Z(t) = i \} = q_{ij} \Delta t + O(\Delta t)$$

$$p_{ii}(\Delta t) = \Pr \{ Z(t + \Delta t) = i \mid Z(t) = i \} = 1 + q_{ii} \Delta t + O(\Delta t)$$

The C-K equation can be written as:

$$\begin{aligned} p_{ij}(t + \Delta t) &= \sum_k p_{ik}(t) p_{kj}(\Delta t) \\ &= p_{ij}(t) p_{jj}(\Delta t) + \sum_{k:k \neq j} p_{ik}(t) p_{kj}(\Delta t) \end{aligned}$$

$$p_{ij}(t + \Delta t) = p_{ij}(t)(1 + q_{jj} \Delta t) + \sum_{k:k \neq j} p_{ik}(t) q_{kj} \Delta t + O(\Delta t)$$

From the above:

$$\frac{p_{ij}(t + \Delta t) - p_{ij}(t)}{\Delta t} = p_{ij}(t) q_{jj} + \sum_{k:k \neq j} p_{ik}(t) q_{kj} + \frac{O(\Delta t)}{\Delta t}$$

Taking the limit as $\Delta t \rightarrow 0$,

$$\frac{d p_{ij}(t)}{d t} = \sum_k p_{ik}(t) q_{kj} \quad \text{with initial condition} \quad p_{ij}(0) = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

The Transition Rate Matrix

Since the transition to a state from time t to $(t + \Delta t)$ is the certain event:

$$1 = \sum_j p_{ij}(\Delta t) = 1 + q_{ii} \Delta t + \sum_{j:j \neq i} q_{ij} \Delta t$$

$$q_{ii} = - \sum_{j:j \neq i} q_{ij}$$

Define the transition rate matrix (infinitesimal generator) \mathbf{Q} of the process as:

$$\mathbf{Q} = [q_{ij}] \quad \text{where} \quad \begin{array}{ll} q_{ij} \geq 0 & i \neq j \\ q_{ii} < 0 & q_{ii} = - \sum_{j:j \neq i} q_{ij} \end{array}$$

The row sum of the transition rate matrix \mathbf{Q} is equal to 0.

In matrix form, the C-K equations become:

$$\mathbf{P}'(t) = \mathbf{P}(t) \cdot \mathbf{Q} \quad ; \quad \mathbf{P}(0) = \mathbf{I}$$

The State Probability Vector

Let $\mathbf{p}(t)$ be the state probability vector in a homogeneous CTMC, and let $\mathbf{p}(0)$ be the initial state probability vector (the initial condition). We have:

$$\mathbf{p}(t) = \mathbf{p}(0) \cdot \mathbf{P}(t)$$

Differentiating both sides:

$$\mathbf{p}'(t) = \mathbf{p}(0) \cdot \mathbf{P}'(t) = \mathbf{p}(0) \cdot \mathbf{P}(t) \cdot \mathbf{Q}$$

From which we derive the state probability equation:

$$\mathbf{p}'(t) = \mathbf{p}(t) \cdot \mathbf{Q}$$

with initial condition $\mathbf{p}(0)$

The state probability equation has formal solution:

$$\mathbf{p}(t) = \mathbf{p}(0) \cdot e^{\mathbf{Q}t}$$

where:

$$e^{\mathbf{Q}t} = \mathbf{I} + \mathbf{Q}t + \frac{1}{2}(\mathbf{Q}t)^2 + \dots = \sum_{i=0}^{\infty} \frac{1}{i!} (\mathbf{Q}t)^i$$

The Laplace Transform of the State Probability Equation

The state probability equation can be written explicitly:

$$\begin{cases} p_1'(t) = p_1(t) q_{11} + p_2(t) q_{21} + \dots + p_N(t) q_{N1} \\ p_2'(t) = p_1(t) q_{12} + p_2(t) q_{22} + \dots + p_N(t) q_{N2} \\ \dots \quad \dots \end{cases}$$

Denoting the Laplace transform: $\mathcal{L}[p_i(t)] = p_i^*(s)$, the Laplace transform of the state probability equation becomes:

$$\begin{cases} s p_1^*(s) - p_1(0) = p_1^*(s) q_{11} + p_2^*(s) q_{21} + \dots + p_N^*(s) q_{N1} \\ s p_2^*(s) - p_2(0) = p_1^*(s) q_{12} + p_2^*(s) q_{22} + \dots + p_N^*(s) q_{N2} \\ \dots \quad \dots \end{cases}$$

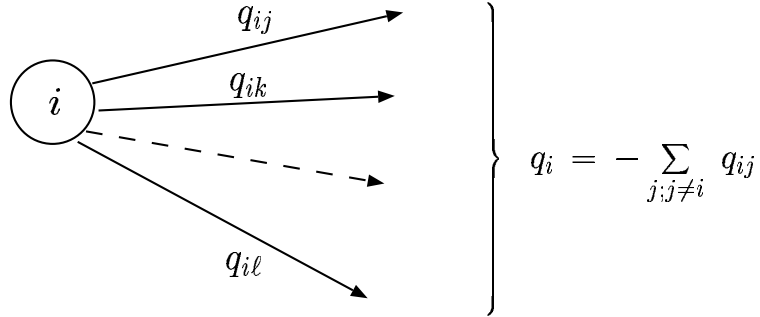
$$\begin{cases} p_1^*(s) (s - q_{11}) - p_2^*(s) q_{21} - \dots - p_N^*(s) q_{N1} = p_1(0) \\ -p_1^*(s) q_{12} + p_2^*(s) (s - q_{22}) - \dots - p_N^*(s) q_{N2} = p_2(0) \\ \dots \quad \dots \end{cases}$$

In matrix form, the above equations become:

$$\mathbf{p}^*(s) (s \mathbf{I} - \mathbf{Q}) = \mathbf{p}_0 \quad \Rightarrow \quad \mathbf{p}^*(s) = \mathbf{p}_0 (s \mathbf{I} - \mathbf{Q})^{-1}$$

Sojourn time in state i

We isolate state i by deleting transitions entering state i . We have:



$$\frac{dp_i(t)}{dt} = -p_i(t) q_i \quad p_i(0) = 1$$

Where: $q_i = -q_{ii} = \sum_{j:j \neq i} q_{ij}$ is a negative constant equal to the sum of the rates out of state i .

Solution of the above equation is:

$$p_i(t) = 1 - e^{-q_i t}$$

The sojourn time in each state is exponentially distributed with a rate equal to the sum of the exit rates.

The probability that the sojourn time in state i terminates by a transition toward state j , is given by:

$$p_{ij}(t) = \frac{q_{ij}}{q_i} e^{-q_i t}$$

Expected State Occupancy in $(0 - t)$

Let $\theta_i(t)$ be the random variable representing the time spent by the CTMC $Z(t)$ in state s_i in the interval $(0 - t)$.

To evaluate the expected value of $\theta_i(t)$, let us introduce an indicator process $y(t)$ defined as follows:

$$\begin{cases} y(t) = 1 & \text{if } Z(t) = i \\ y(t) = 0 & \text{if } Z(t) \neq i \end{cases}$$

By construction:

$$\theta_i(t) = \int_0^t y(u) du$$

with initial condition $\theta_i(0) = 0$.

Hence:

$$\begin{aligned} E[\theta_i(t)] &= E\left[\int_0^t y(u) du\right] = \int_0^t E[y(u)] du \\ &= \int_0^t 0 \cdot Pr\{y(t) = 0\} + 1 \cdot Pr\{y(t) = 1\} du \\ &= \int_0^t p_i(u) du \end{aligned}$$

Introducing the vector $\boldsymbol{\theta}(t)$ whose entries are the $E[\theta_i(t)]$, we can write:

$$\boldsymbol{\theta}(t) - \boldsymbol{\theta}(0) = \int_0^t \mathbf{p}(u) du$$

$$\boldsymbol{\theta}(t) = \boldsymbol{\theta}(0) + \mathbf{p}_0 (\mathbf{I}t + \frac{t^2}{2} \mathbf{Q} + \dots + \frac{t^{i+1}}{(i+1)!} \mathbf{Q}^i + \dots)$$

Classification of states and stationary distribution

The classification of states for a CTMC is similar to the DTMC case. Given a state i , if the ultimate return to that state is the certain event, the state is called *recurrent*, if the ultimate return has probability less than 1, the state is called *transient*.

An absorbing state is a state with no outgoing arcs: state i is absorbing if $q_{ij} = 0$ for any $j \neq i$.

A state j is *reachable* from i for some $t > 0$, if $p_{ij}(t) > 0$.

The state space of a CTMC can be partitioned into a set of transient states and closed sets of recurrent states.

A CTMC is *irreducible* if every state is reachable from every other state.

An irreducible CTMC reaches a steady-state condition as $t \rightarrow \infty$ independently of the initial condition.

$$\lim_{t \rightarrow \infty} p_i(t) = \pi_i$$

If the limit exists then: $\lim_{t \rightarrow \infty} \frac{dp_i(t)}{dt} = 0$

and the steady state matrix equation becomes:

$$\boldsymbol{\pi} \cdot \mathbf{Q} = \mathbf{0} \quad \text{with} \quad \sum_{i=1}^N \pi_i = 1$$

Properties of the steady-state distribution

Similarly to the discrete case, the equilibrium distribution for an irreducible CTMC has the following properties:

- ◇ for all initial conditions, the occupancy state probability $p_i(t)$ tends to a constant value π_i as $t \rightarrow \infty$, and the π_i 's form a probability distribution.
- ◇ if the initial probability is π_i , then $p_i(t) = \pi_i$ for all t ;
- ◇ the proportion of time spent in state i in the interval $(0 - t)$ tends to π_i as $t \rightarrow \infty$:

$$\lim_{t \rightarrow \infty} \frac{E[\theta_i]}{t} = \pi_i$$

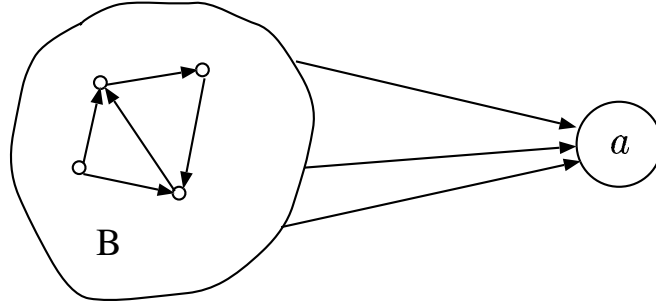
- ◇ the steady-state probabilities satisfy a system of ordinary linear equations.

$$\boldsymbol{\pi} \cdot \mathbf{Q} = \mathbf{0} \quad \text{with} \quad \boldsymbol{\pi} \cdot \mathbf{e}^T = 1$$

- ◇ the steady state equation can be interpreted as a probability balance equation (for every state the probability flow-in equals the probability flow-out)

CTMC with Absorbing States

Let state a be an absorbing state. We can partition the Markov equation as follows (being the row corresponding to the absorbing state equal to 0).



$$[\mathbf{p}'(t) \ p'_a(t)] = [\mathbf{p}(t) \ p_a(t)] \left[\begin{array}{c|c} \mathbf{B} & \mathbf{A} \\ \hline - & - \\ \mathbf{0} & 0 \end{array} \right]$$

where the square matrix \mathbf{B} groups the transition rates inside the transient states and the column vector $\mathbf{A} = -\mathbf{B} \mathbf{e}^T$ the rates from the transient states to the absorbing state.

Solving the above equations in partitioned form, we get:

$$\begin{cases} \mathbf{p}'(t) = \mathbf{p}(t) \mathbf{B} \\ p'_a(t) = \mathbf{p}(t) \mathbf{A} \end{cases}$$

$$\begin{cases} \mathbf{p}(t) = \mathbf{p}_0 e^{\mathbf{B}t} \\ p'_a(t) = \mathbf{p}_0 e^{\mathbf{B}t} \mathbf{A} \end{cases}$$

Given τ_a is the time to reach the absorbing state from $t = 0$ (time to absorption), we have:

$$\begin{aligned} F_a(t) &= Pr\{\tau_a \leq t\} = Pr\{Z(t) = a\} = p_a(t) \\ &= 1 - \mathbf{p}(t) \mathbf{e}^T = 1 - \mathbf{p}_0 e^{\mathbf{B}t} \mathbf{e}^T \end{aligned}$$

CTMC with Absorbing States in Laplace transform

$$\begin{bmatrix} s \mathbf{p}^*(s) - \mathbf{p}_0 & s p_a^*(s) \end{bmatrix} = \begin{bmatrix} \mathbf{p}^*(s) & p_a^*(s) \end{bmatrix} \left| \begin{array}{c|c} \mathbf{B} & \mathbf{A} \\ \hline - & - \\ \hline \mathbf{0} & 0 \end{array} \right|$$

$$\begin{cases} s \mathbf{p}^*(s) - \mathbf{p}_0 = \mathbf{p}^*(s) \mathbf{B} \\ s p_a^*(s) = \mathbf{p}^*(s) \mathbf{A} \end{cases}$$

$$\begin{cases} \mathbf{p}^*(s) = \mathbf{p}_0 (s \mathbf{I} - \mathbf{B})^{-1} \\ p_a^*(s) = \frac{1}{s} \mathbf{p}^*(s) \mathbf{A} = \frac{1}{s} \mathbf{p}_0 (s \mathbf{I} - \mathbf{B})^{-1} \mathbf{A} \end{cases}$$

It turns out that:

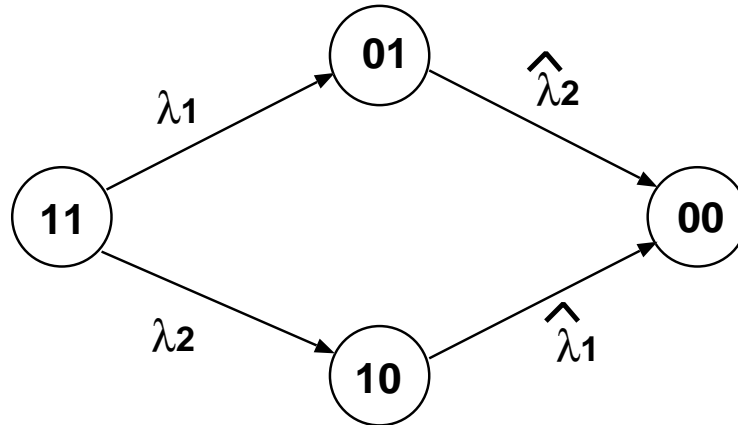
$$\begin{aligned} F_a^*(s) &= \frac{1}{s} \mathbf{p}_0 (s \mathbf{I} - \mathbf{B})^{-1} \mathbf{A} \\ f_a^*(s) &= s F_a^*(s) = \mathbf{p}_0 (s \mathbf{I} - \mathbf{B})^{-1} \mathbf{A} \end{aligned}$$

Resorting to the moment theorem for Laplace transforms, we can evaluate the mean time to absorption (with $\mathbf{A} = -\mathbf{B} \mathbf{e}^T$):

$$\begin{aligned} E[\tau_a] &= (-1) \frac{d f_a^*(s)}{d s} \Big|_{s=0} \\ &= (-1) \mathbf{p}_0 (s \mathbf{I} - \mathbf{B})^{-2} \mathbf{A} \Big|_{s=0} \\ &= \mathbf{p}_0 (-\mathbf{B})^{-1} \mathbf{e}^T \end{aligned}$$

System of two Dependent Components

Markov Analysis - 1



The transition rate matrix \mathbf{Q} assumes the form:

$$\begin{array}{c}
 \mathbf{Q} = \begin{array}{c|cccc}
 & (1,1) & (0,1) & (1,0) & (0,0) \\
 \hline
 (1,1) & -(\lambda_1 + \lambda_2) & \lambda_1 & \lambda_2 & 0 \\
 (0,1) & 0 & -\hat{\lambda}_2 & 0 & \hat{\lambda}_2 \\
 (1,0) & 0 & 0 & -\hat{\lambda}_1 & \hat{\lambda}_1 \\
 (0,0) & 0 & 0 & 0 & 0
 \end{array}
 \end{array}$$

System of two Dependent Components - 2

The solution equation for the state probabilities is:

$$\begin{vmatrix} p_1'(t) & p_2'(t) & p_3'(t) & p_4'(t) \end{vmatrix} = \begin{vmatrix} p_1(t) & p_2(t) & p_3(t) & p_4(t) \end{vmatrix} \cdot \begin{vmatrix} -(\lambda_1 + \lambda_2) & \lambda_1 & \lambda_2 & 0 \\ 0 & -\hat{\lambda}_2 & 0 & \hat{\lambda}_2 \\ 0 & 0 & -\hat{\lambda}_1 & \hat{\lambda}_1 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

From the matrix equation the following set of linear differential equations is obtained:

$$\frac{d p_1(t)}{d t} = -(\lambda_1 + \lambda_2) p_1(t)$$

$$\frac{d p_2(t)}{d t} = \lambda_1 p_1(t) - \hat{\lambda}_2 p_2(t)$$

$$\frac{d p_3(t)}{d t} = \lambda_2 p_1(t) - \hat{\lambda}_1 p_3(t)$$

$$\frac{d p_4(t)}{d t} = \hat{\lambda}_2 p_2(t) + \hat{\lambda}_1 p_3(t)$$

System of two Dependent Components - 3

Let us assume, as initial condition, that the system is in the good state $s_1 = \{0, 0\}$ at time $t = 0$ with probability 1.

$$p_1(0) = 1, \quad p_2(0) = 0, \quad p_3(0) = 0, \quad p_4(0) = 0$$

The solution of the set of linear differential equations can be obtained by resorting to the Laplace transform method. Let $p_i^*(s)$ denote the Laplace transform of $p_i(t)$. We get:

$$s p_1^*(s) - 1 = -(\lambda_1 + \lambda_2) p_1^*(s)$$

$$s p_2^*(s) = \lambda_1 p_1^*(s) - \hat{\lambda}_2 p_2^*(s)$$

$$s p_3^*(s) = \lambda_2 p_1^*(s) - \hat{\lambda}_1 p_3^*(s)$$

$$s p_4^*(s) = \hat{\lambda}_2 p_2^*(s) + \hat{\lambda}_1 p_3^*(s)$$

The state probabilities in the time domain are:

$$p_1(t) = e^{-(\lambda_1 + \lambda_2)t}$$

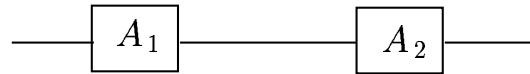
$$p_2(t) = \frac{\lambda_1}{\lambda_1 + \lambda_2 - \hat{\lambda}_2} (e^{-\hat{\lambda}_2 t} - e^{-(\lambda_1 + \lambda_2)t})$$

$$p_3(t) = \frac{\lambda_2}{\lambda_1 + \lambda_2 - \hat{\lambda}_1} (e^{-\hat{\lambda}_1 t} - e^{-(\lambda_1 + \lambda_2)t})$$

$$p_4(t) = 1 - p_1(t) - p_2(t) - p_3(t)$$

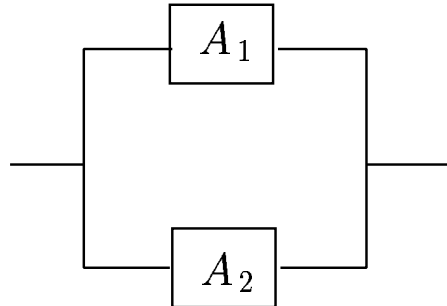
System of two Dependent Components - 4

Series System:



$$R_{ser}(t) = p_1(t) = e^{-(\lambda_1 + \lambda_2)t}$$

Parallel System:

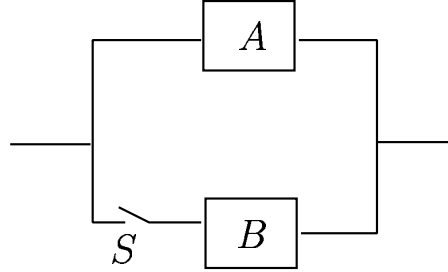


$$R_{par}(t) = p_1(t) + p_2(t) + p_3(t) =$$

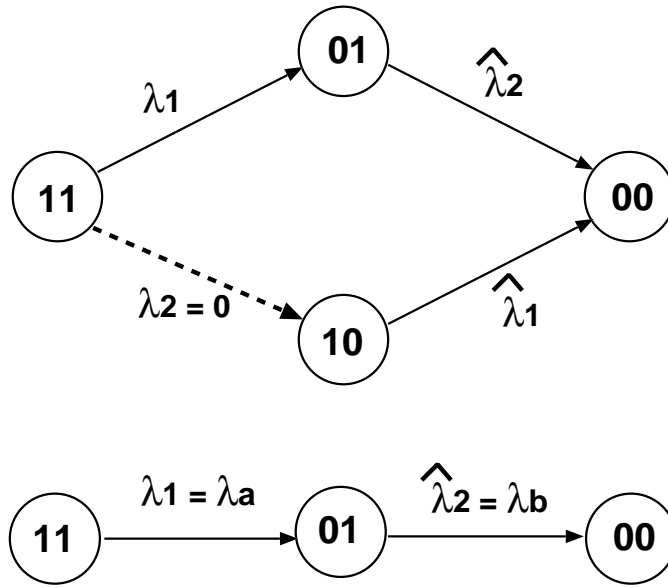
$$\begin{aligned} &= e^{-(\lambda_1 + \lambda_2)t} \\ &+ \frac{\lambda_1}{\lambda_1 + \lambda_2 - \hat{\lambda}_2} (e^{-\hat{\lambda}_2 t} - e^{-(\lambda_1 + \lambda_2)t}) \\ &+ \frac{\lambda_2}{\lambda_1 + \lambda_2 - \hat{\lambda}_1} (e^{-\hat{\lambda}_1 t} - e^{-(\lambda_1 + \lambda_2)t}) \end{aligned}$$

System of two Dependent Components - 5

Stand-by redundancy:



Since component 2 is not operating in state $s_1 = \{1, 1\}$, we have $\lambda_2 = 0$. The Markov graph becomes in this case:

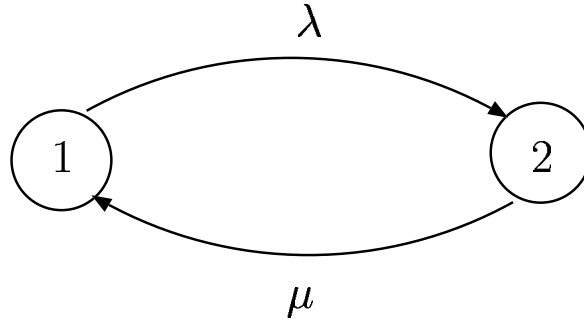


$$R_{standby}(t) = \frac{\lambda_a}{\lambda_a - \lambda_b} e^{-\lambda_b t} - \frac{\lambda_b}{\lambda_a - \lambda_b} e^{-\lambda_a t}$$

If the two components are identical ($\lambda_a = \lambda_b = \lambda$), the previous equation becomes:

$$R_{standby}(t) = (1 + \lambda t) e^{-\lambda t}$$

Repairable System - Availability



$$\begin{vmatrix} p'_1(t) & p'_2(t) \end{vmatrix} = \begin{vmatrix} p_1(t) & p_2(t) \end{vmatrix} \cdot \begin{vmatrix} -\lambda & \lambda \\ \mu & -\mu \end{vmatrix}$$

Expliciting the matrix equation we obtain:

$$\frac{dp_1(t)}{dt} = -\lambda p_1(t) + \mu p_2(t)$$

$$\frac{dp_2(t)}{dt} = \lambda p_1(t) - \mu p_2(t)$$

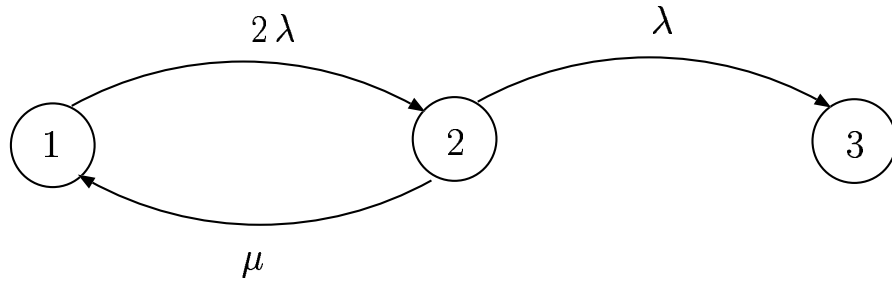
Assuming as initial condition $[p_1(0) = 1, p_2(0) = 0]$, the state probabilities become:

$$p_1(t) = \frac{\mu}{\lambda + \mu} + \frac{\lambda}{\lambda + \mu} e^{-(\lambda + \mu)t}$$

$$p_2(t) = \frac{\lambda}{\lambda + \mu} - \frac{\lambda}{\lambda + \mu} e^{-(\lambda + \mu)t}$$

Two Component System

Identical and Repairable Components - 1



$$\begin{vmatrix} p_1'(t) & p_2'(t) & p_3'(t) \end{vmatrix} = \begin{vmatrix} p_1(t) & p_2(t) & p_3(t) \end{vmatrix} \cdot \begin{vmatrix} -2\lambda & 2\lambda & 0 \\ \mu & -(\lambda + \mu) & \lambda \\ 0 & 0 & 0 \end{vmatrix}$$

Expliciting the matrix equation, we obtain the following set of linear differential equations:

$$\frac{dp_1(t)}{dt} = -2\lambda p_1(t) + \mu p_2(t)$$

$$\frac{dp_2(t)}{dt} = 2\lambda p_1(t) - (\lambda + \mu) p_2(t)$$

$$\frac{dp_3(t)}{dt} = \lambda p_2(t)$$

Two Component System Identical and Repairable Components - 2

We resort to the Laplace transform method.

$$s p_1^*(s) - 1 = -2\lambda p_1^*(s) + \mu p_2^*(s)$$

$$s p_2^*(s) = 2\lambda p_1^*(s) - (\lambda + \mu) p_2^*(s)$$

$$s p_3^*(s) = \lambda p_2^*(s)$$

Solving the algebraic set of equations:

$$p_3^*(s) = \frac{2\lambda^2}{s[s^2 + (3\lambda + \mu)s + 2\lambda^2]}$$

Inverting by means of the partial fraction expansion:

$$R(t) = 1 - p_3(t) = \frac{\alpha_2}{\alpha_1 - \alpha_2} e^{-\alpha_1 t} - \frac{\alpha_1}{\alpha_1 - \alpha_2} e^{-\alpha_2 t}$$

where α_1 and α_2 are roots of the equation:

$$s^2 + (3\lambda + \mu)s + 2\lambda^2 = (s + \alpha_1)(s + \alpha_2)$$